

Adv ML for Gen-AI

Discrete Generative Model

<https://ml-graph.github.io/spring-2026/>

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Assistant Professor

Department of Computer Science

University of Oregon

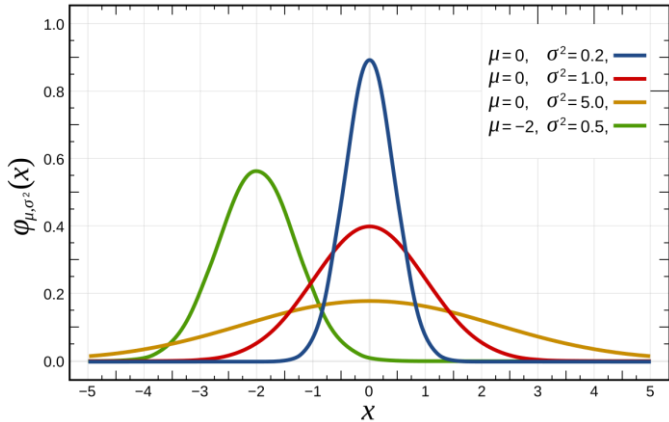
Personal: <https://yuwang0103.github.io/>

Lab: <https://kindlab-fly.github.io/>



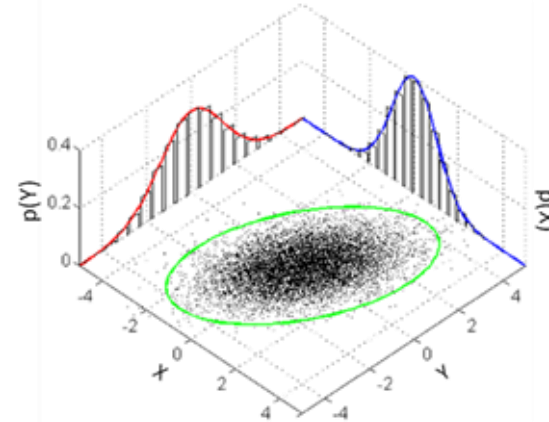
Summary – Distribution

1D Gaussian Distribution

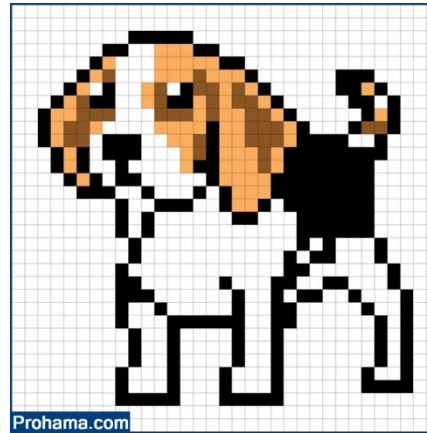
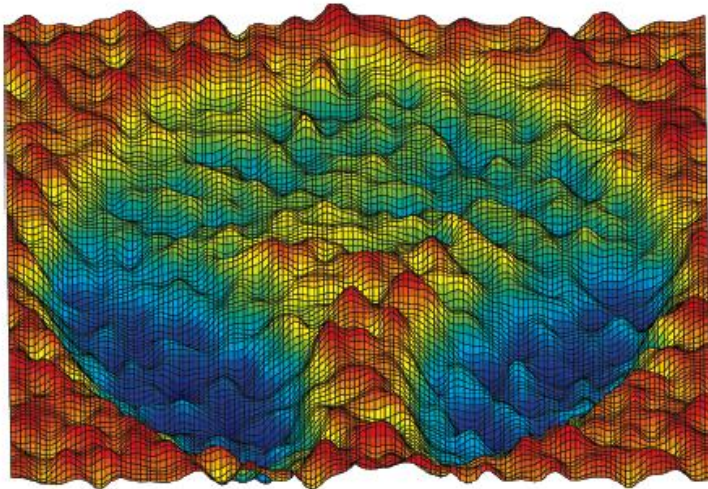


\mathbb{R}

2D Gaussian Distribution



\mathbb{R}^2



$\mathbb{R}^{256 \times 256}$

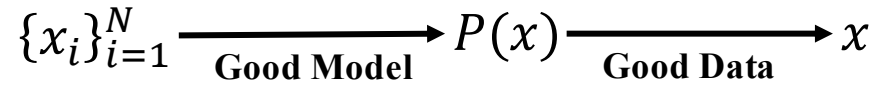


Summary – Existing Generative Methods

Probability distribution of the **objective** based on the **observed data**

- **Machine Learning Methods**

- Gaussian Kernel Density Estimation
- Gaussian Mixture Models



Using **existing function** to estimate what you do not know that can best fit your observation

- **Deep Learning Methods**

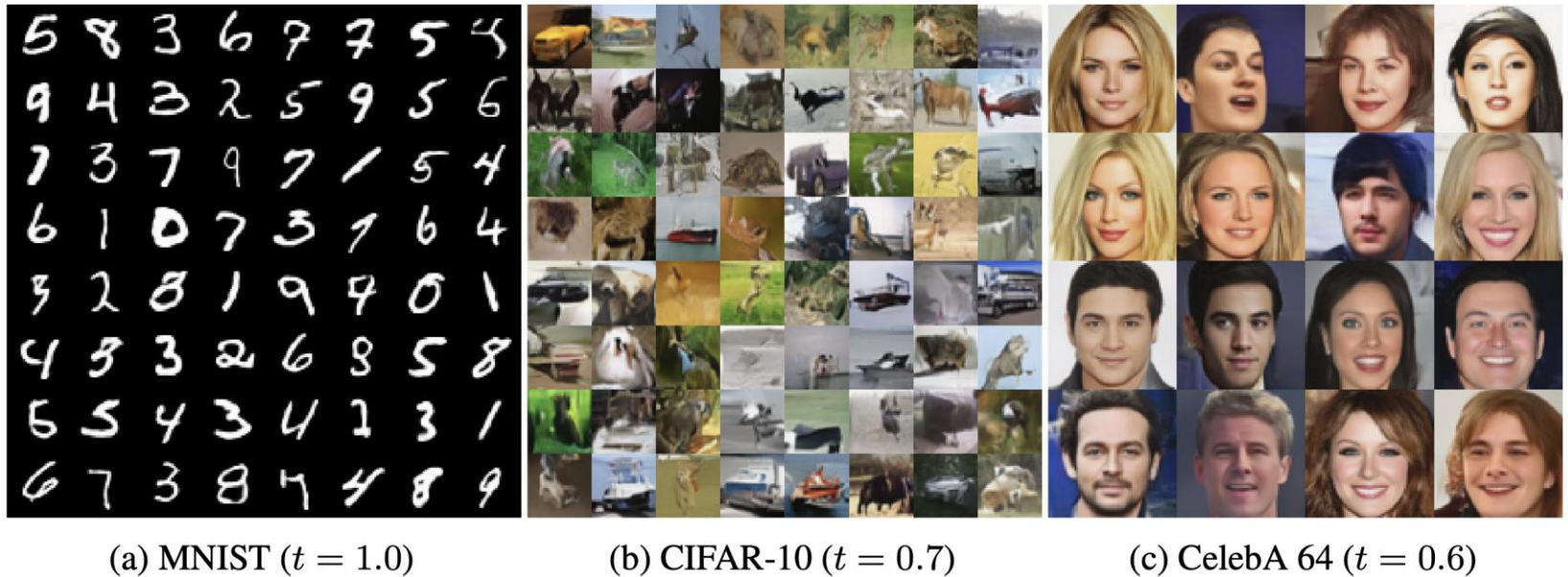
- Auto-Encoder (AE)
- Variational AE (VAE)
- Generative Adversarial Network (GAN)
- Diffusion Model
-

Using **learnable function** to estimate what you do not know that can best fit your observation





Summary – Continuous Generation



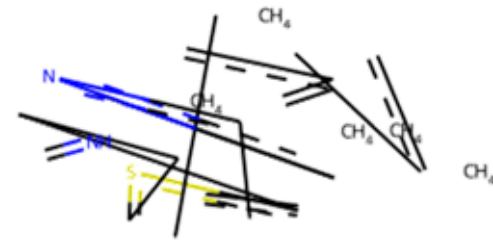
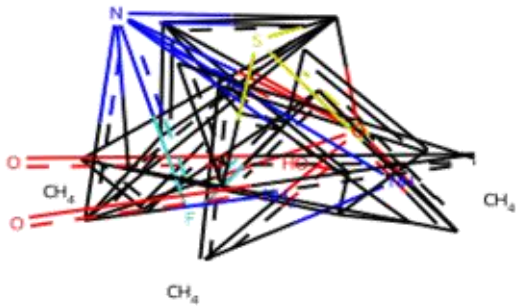
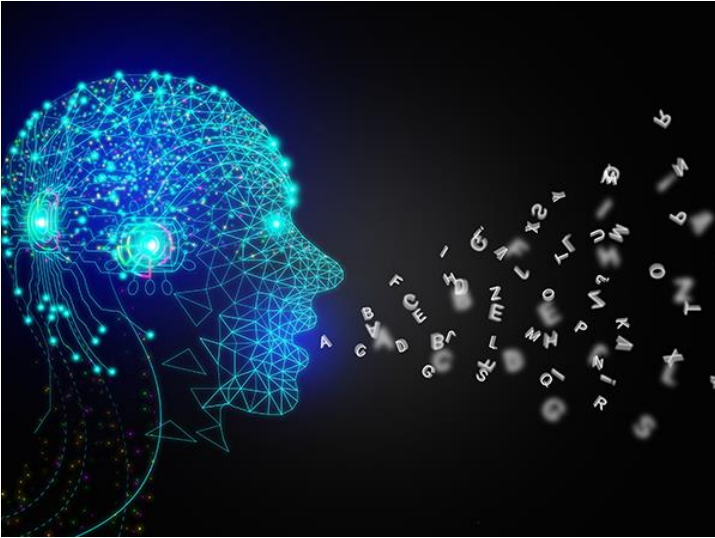
They are all continuous





Problem – Real-world Generation is sometimes discrete

Language Generation



Graph Generation



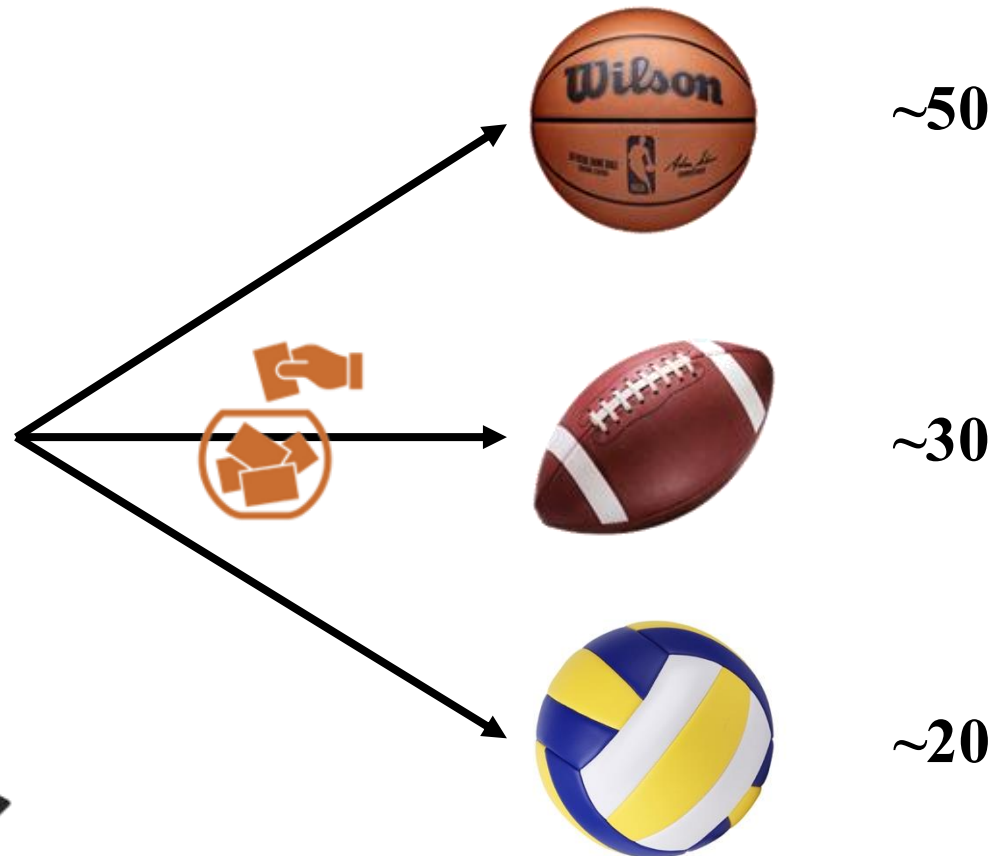
Discrete Generative Model – Ball Example

5 Basketball

2 Volleyball

3 Football

If you Randomly draw 100 times





Discrete Generative Model – Ball Example

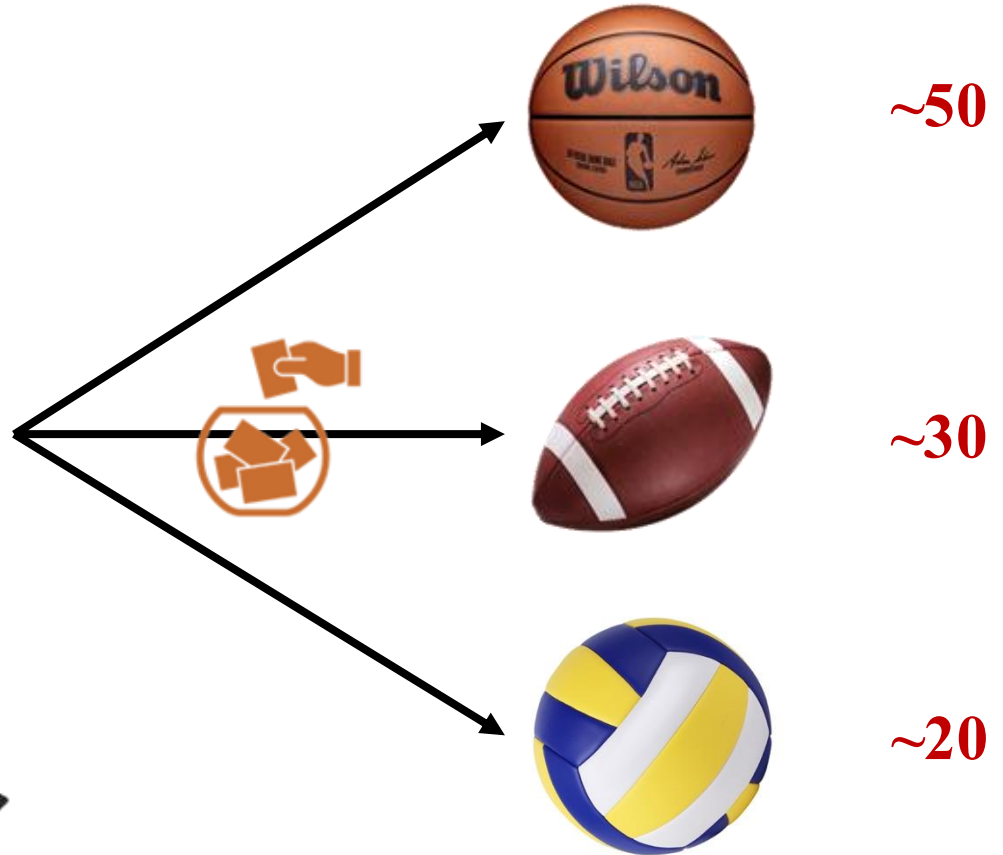
5 Basketball

2 Volleyball

3 Football

But how can you simulate this process on computer?

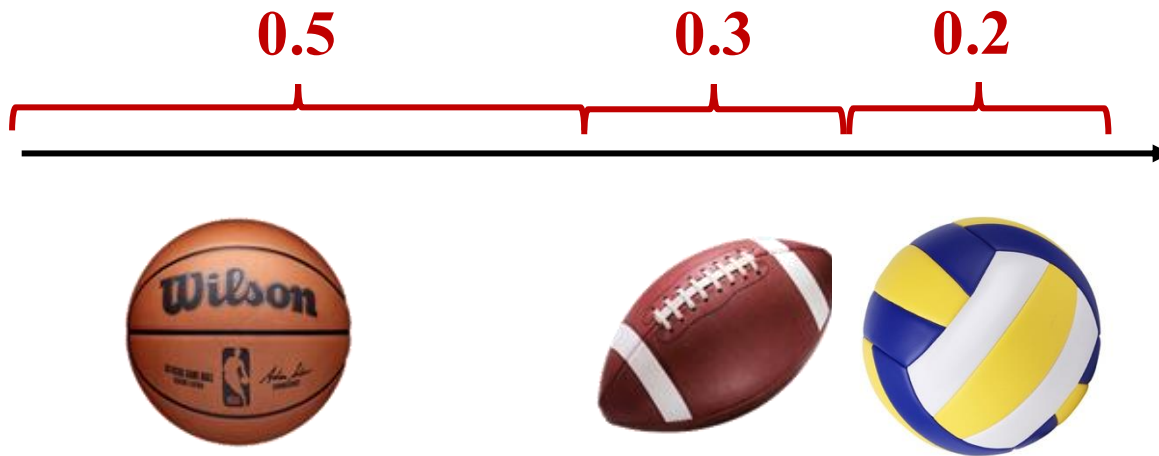
If you Randomly draw 100 times





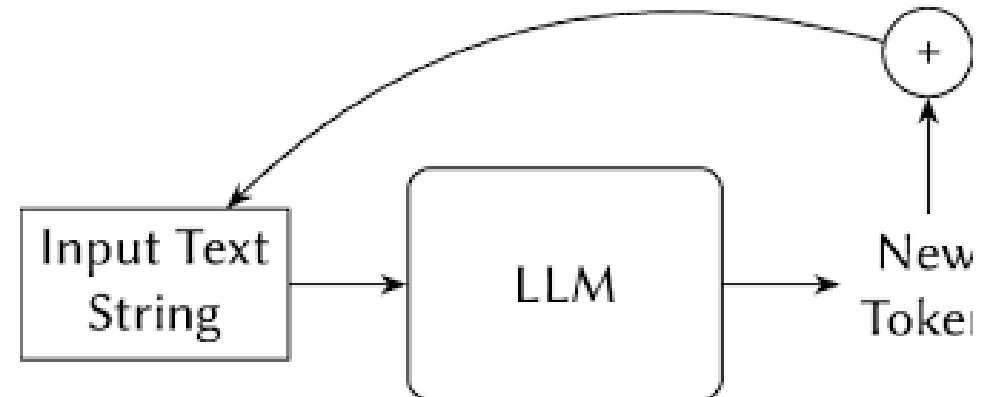
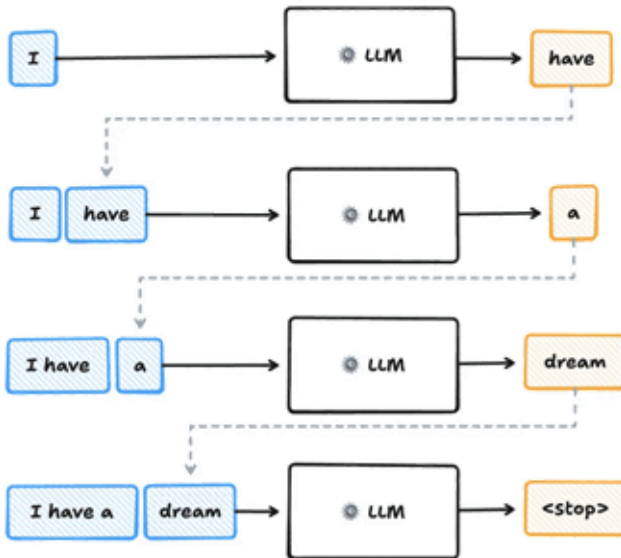
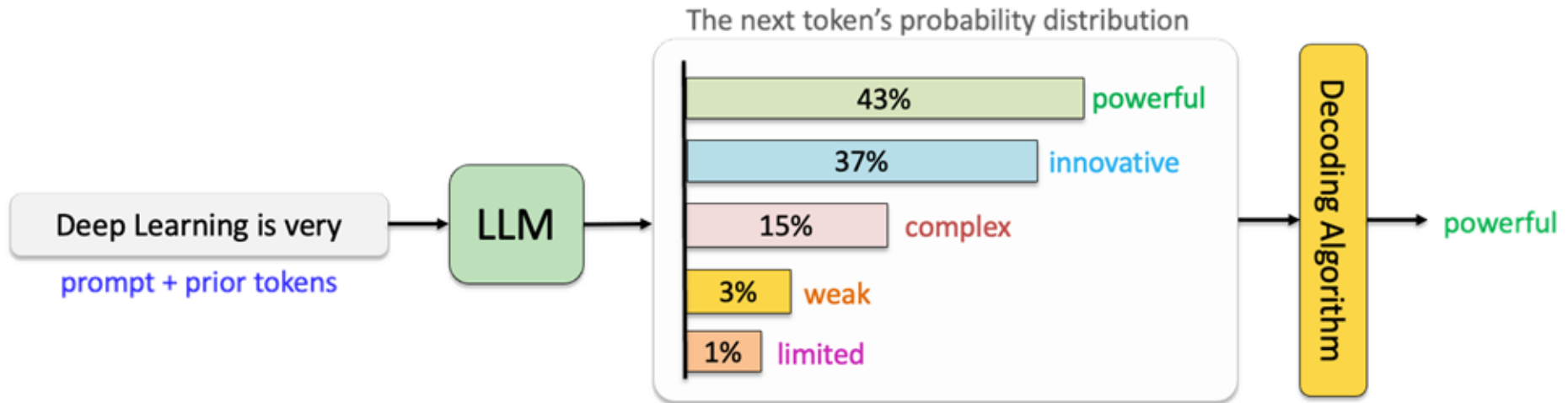
Discrete Generative Model – Ball Example

$$\alpha \sim U(0,1)$$





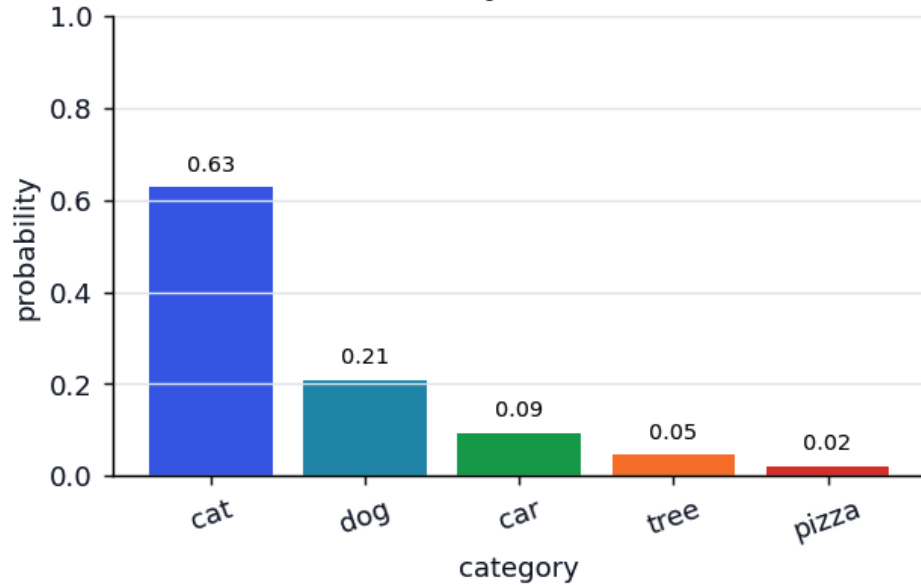
Discrete Generative Model – Language Example



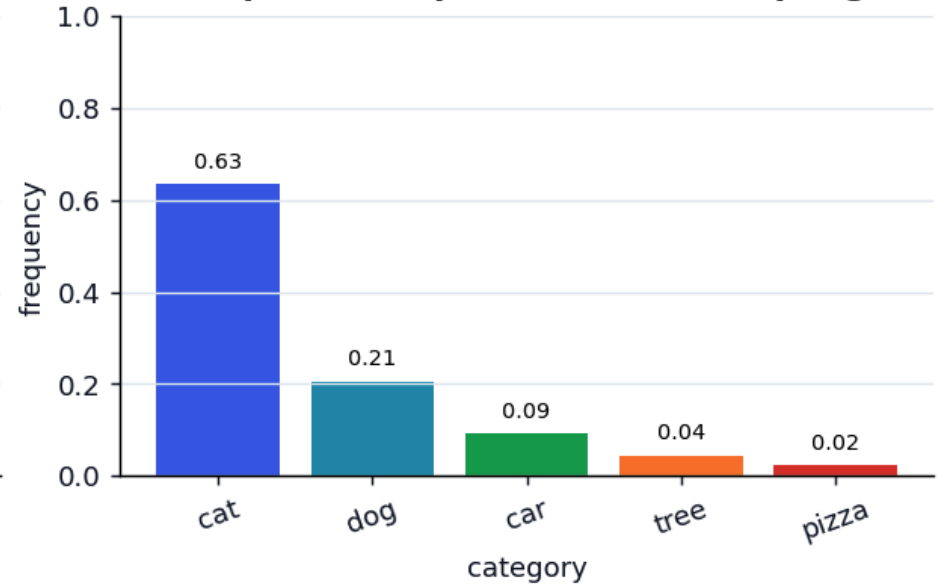


Discrete Generative Model – Language Example

Softmax probabilities



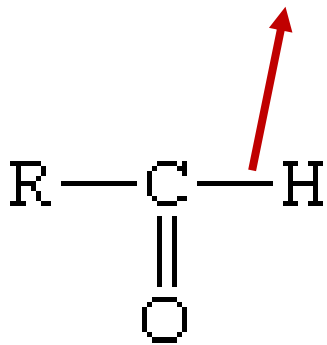
Empirical frequencies after sampling



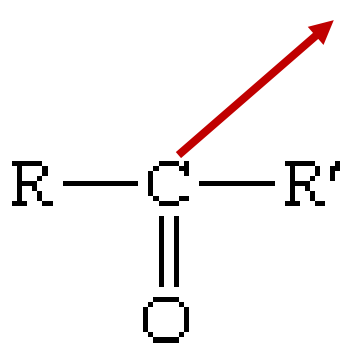


Discrete Generative Model – Graph Example

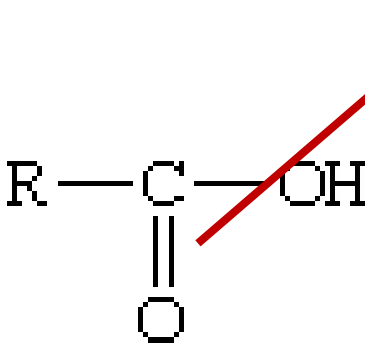
$$p_{\theta}(A_{ij} = 1 | z), \quad p_{\theta}(\text{node}_i = \text{carbon} | z), \quad p_{\theta}(\text{bond}_{ij} = \text{double} | z).$$



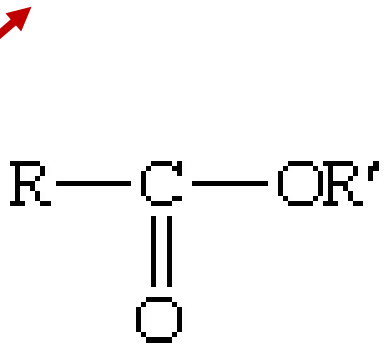
aldehyde



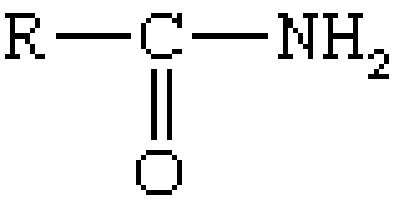
ketone



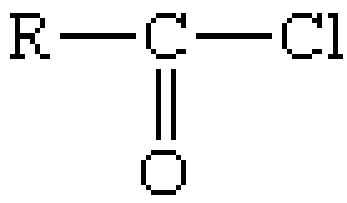
carboxylic acid



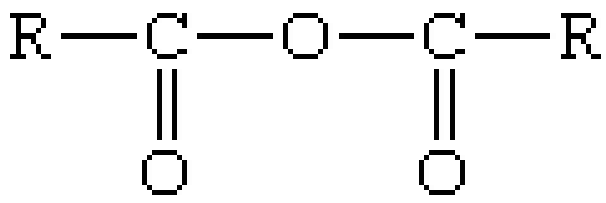
carboxylic ester



amide



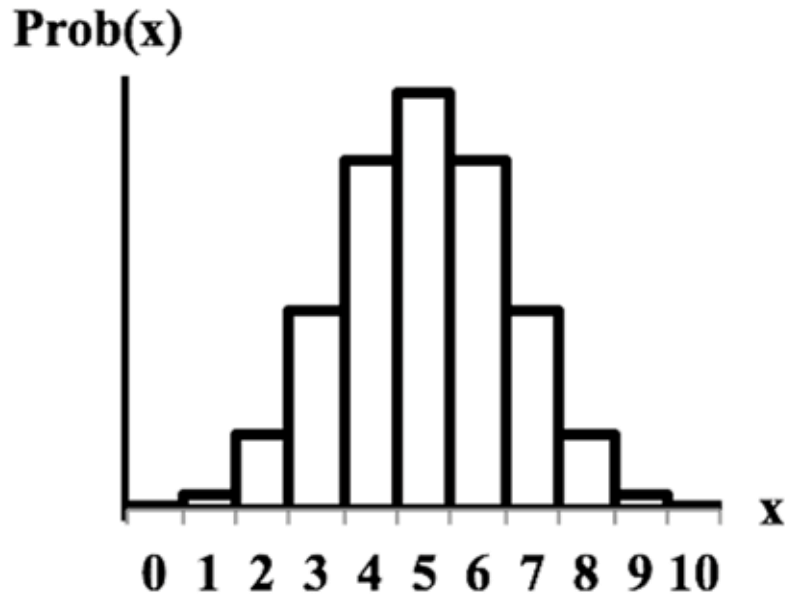
acyl chloride



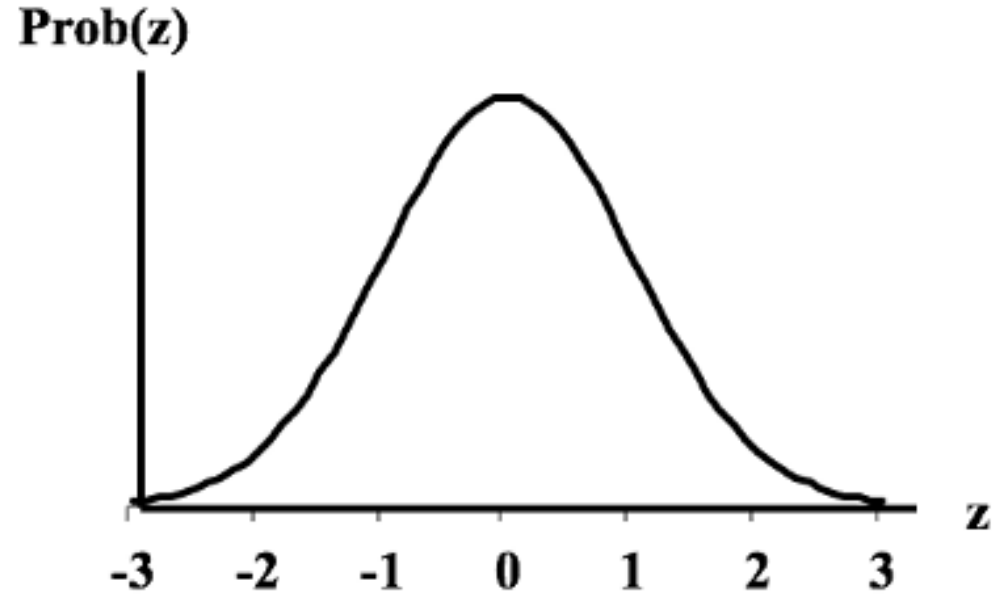
anhydride



Discrete vs Continuous Generative Model



Binomial Distribution
Discrete Data & Discrete
Probability Curve



Standard Normal Distribution
Continuous Data and Continuous
Probability Curve



Overview

- **Statistical Methods**

- Gaussian Estimation (1D or 2D or higher)
- Gaussian Kernel Density Estimation
- Gaussian Mixture Models

- **Machine/Deep Learning Methods**

- Variational AE (VAE)
- Generative Adversarial Network (GAN)
- Diffusion

Continuous version:
Point Cloud/Image/Video

Discrete version:
Graph/Language

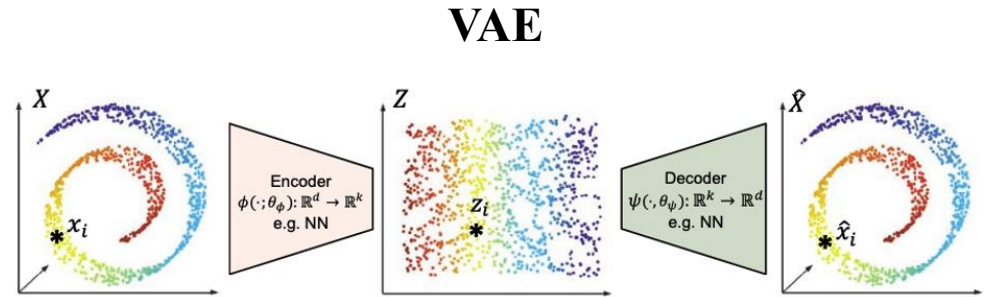
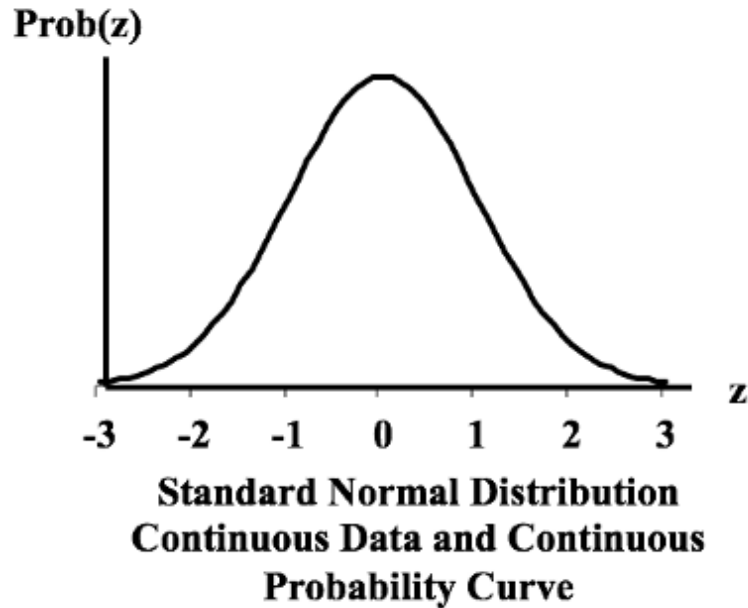


Three key questions

- (1) How to model the distribution?**
- (2) How to train the model to learn the distribution?**
- (3) How to use the learned distribution to generate data?**



Three key questions



Neural Decoder Mapping

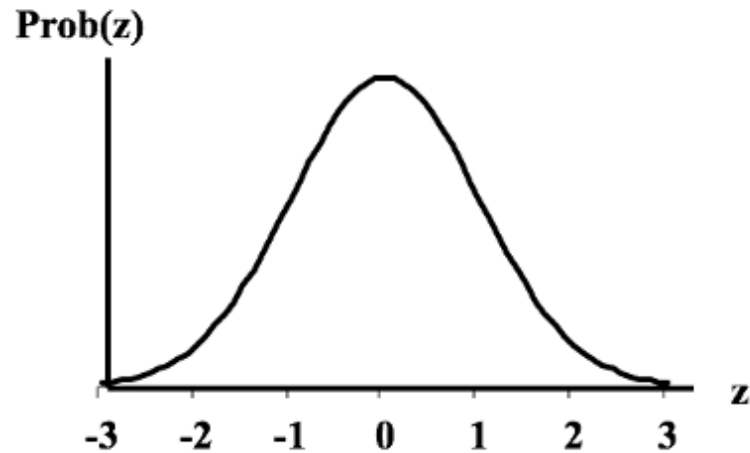
Mean-squared error loss

Sampling Gaussian and transform

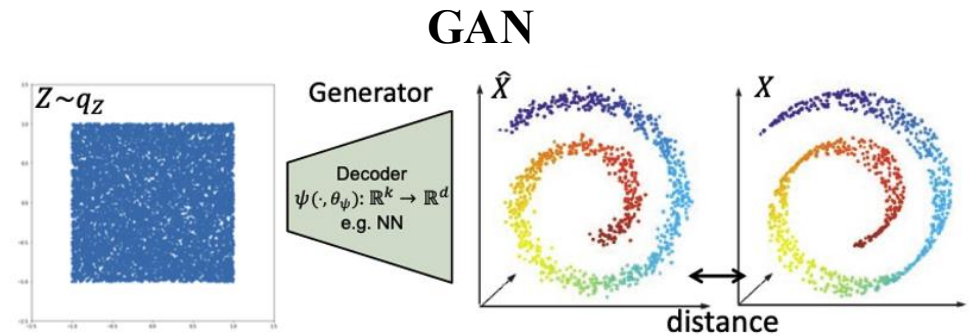
- (1) How to model the distribution?
- (2) How to train the model to learn the distribution?
- (3) How to use the learned distribution to generate data?



Three key questions



Standard Normal Distribution
Continuous Data and Continuous
Probability Curve



Neural Decoder Mapping

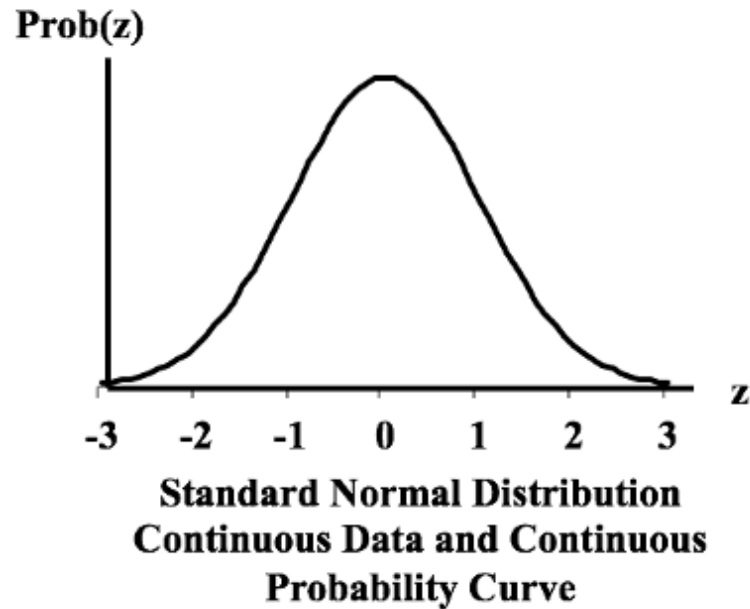
Discriminator – Distribution Difference

Sampling from Gaussian and transform

- (1) How to model the distribution?
- (2) How to train the model to learn the distribution?
- (3) How to use the learned distribution to generate data?



Three key questions



Diffusion



Noise Decoding + Denoise

Mean-squared error loss

Autoregressively sampling and decoding

- (1) How to model the distribution?
- (2) How to train the model to learn the distribution?
- (3) How to use the learned distribution to generate data?



Overview

- **Statistical Methods**

- Gaussian Estimation (1D or 2D or higher)
- Gaussian Kernel Density Estimation
- Gaussian Mixture Models

- **Machine/Deep Learning Methods**

- **Graph** Auto-Encoder (VAE)
- **Graph** Generative Adversarial Network (GAN)
- **Graph** Diffusion (Diffusion)

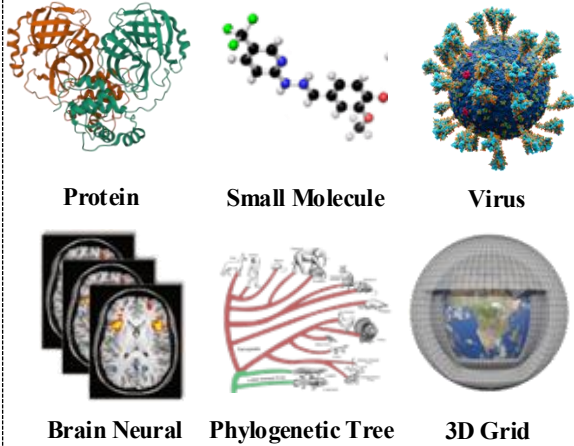
Continuous version:
Point Cloud/Image/Video

Discrete version:
Graph/Language



Graph Definition

Scientific Graph



Gas Network

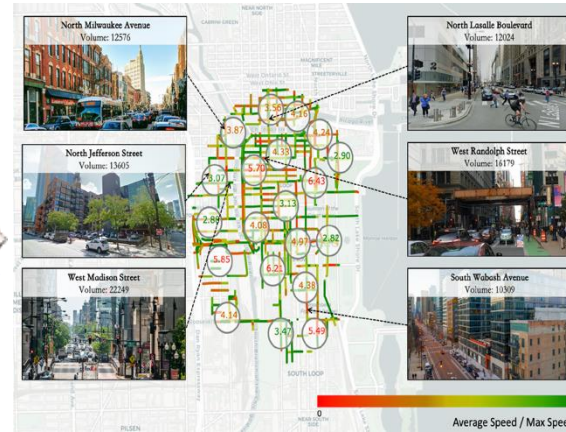


Power Network

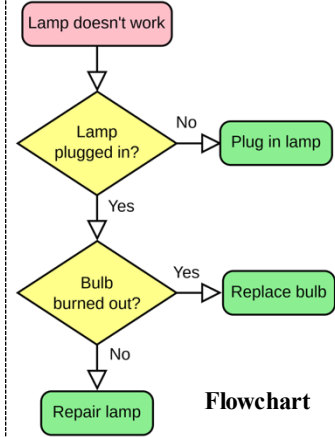


Infrastructure Graph

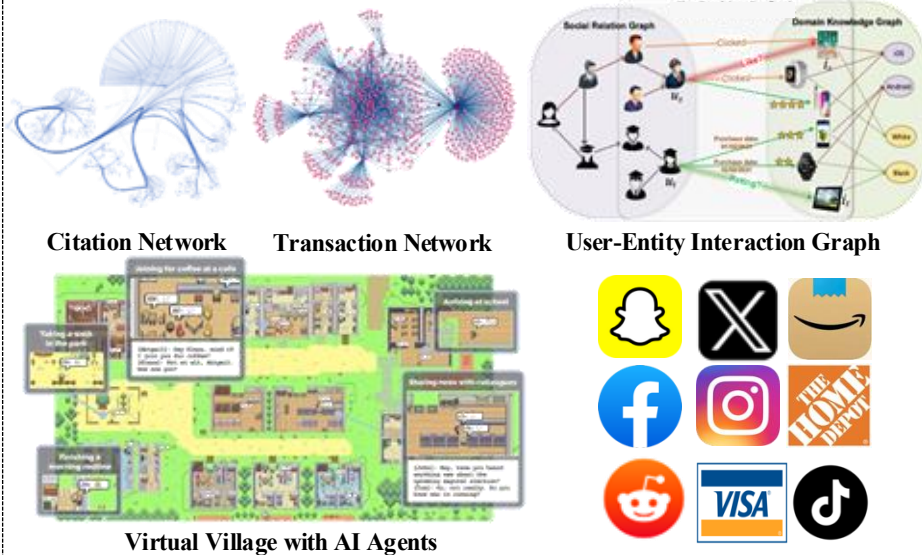
Transportation Network



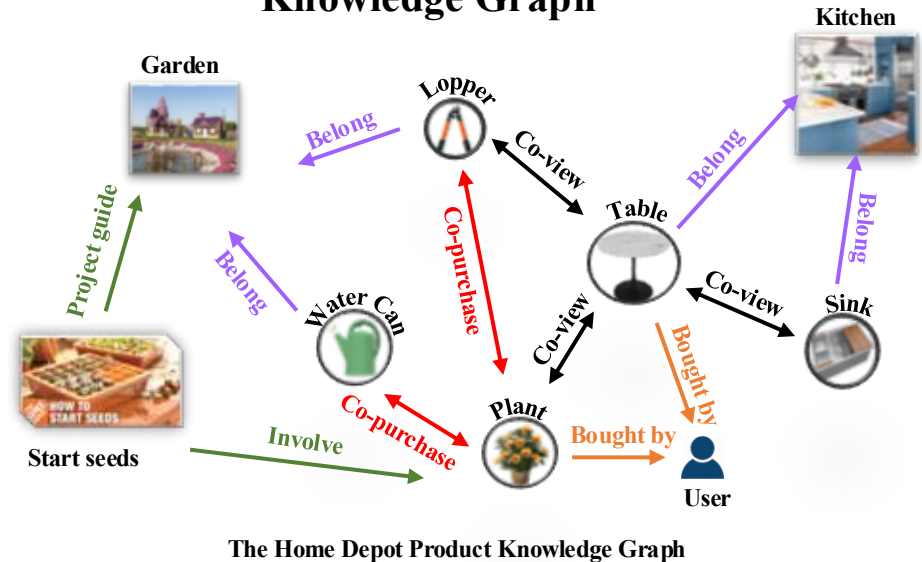
Decision Graph



Social Interaction Graph



Knowledge Graph

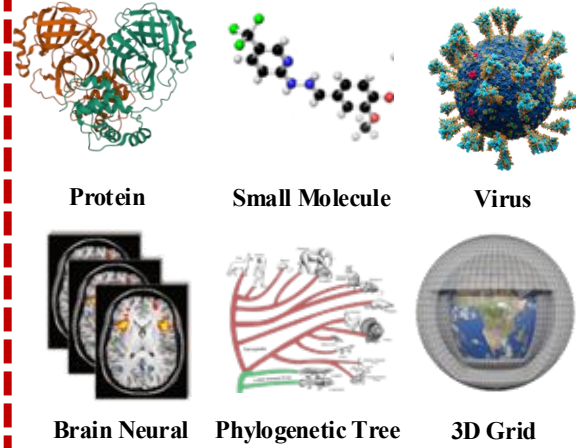




Graph Definition

Microscopic Graph

Scientific Graph



Gas Network

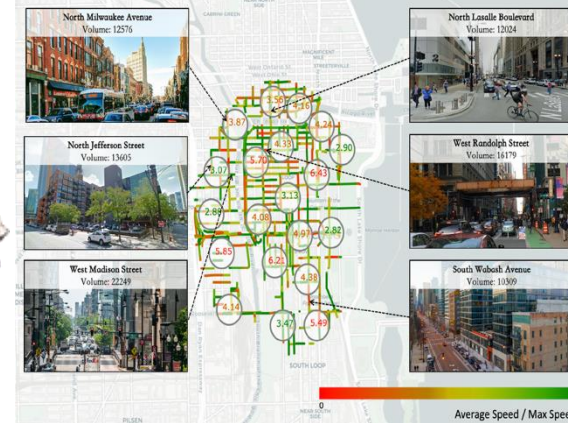


Power Network

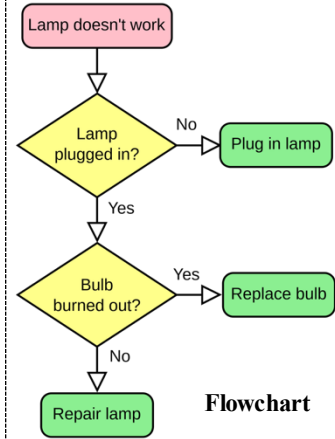


Infrastructure Graph

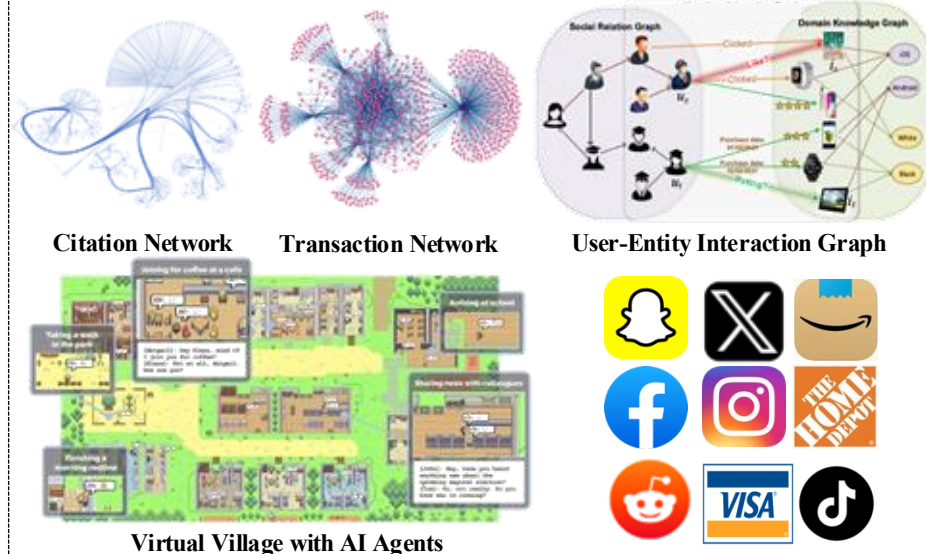
Transportation Network



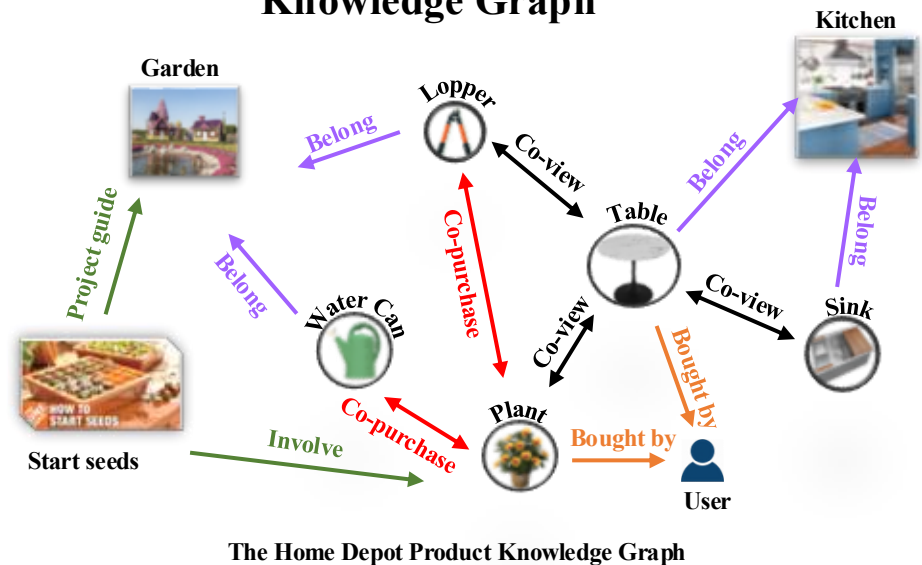
Decision Graph



Social Interaction Graph

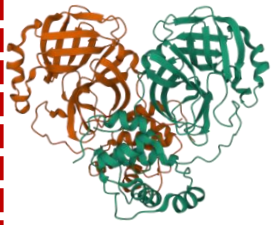


Knowledge Graph

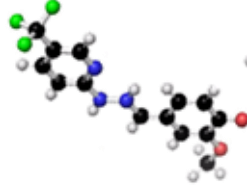




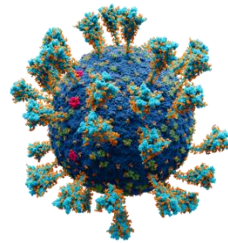
Scientific Graph



Protein



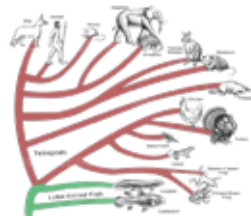
Small Molecule



Virus



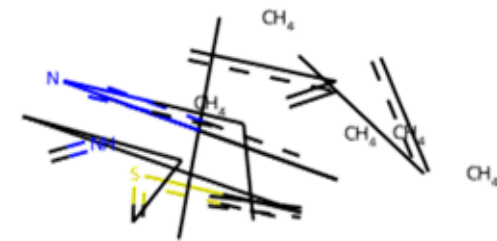
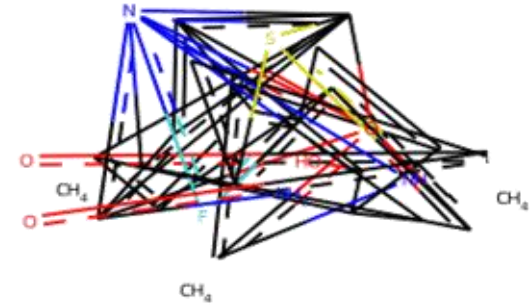
Brain Neural



Phylogenetic Tree



3D Grid



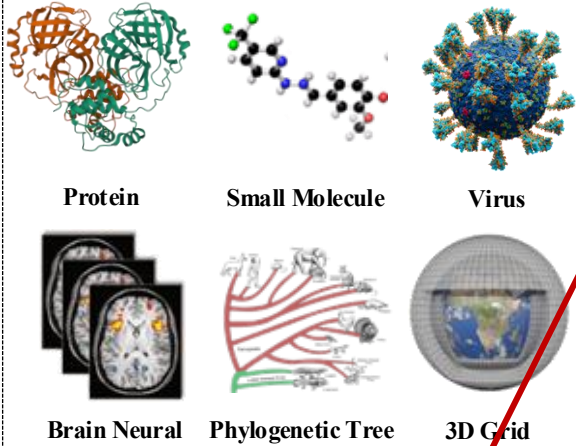
Diffusion



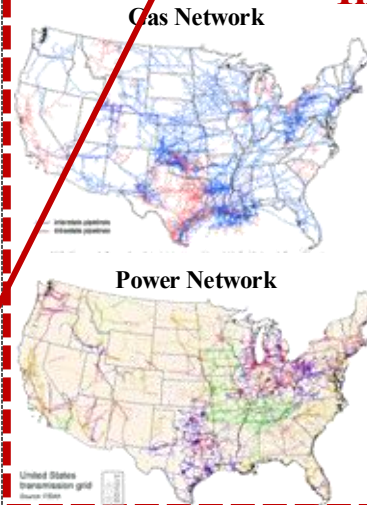
Macroscopic Graph

Graph Definition

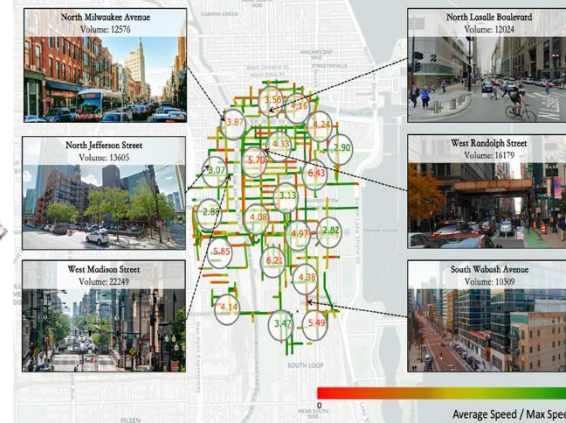
Scientific Graph



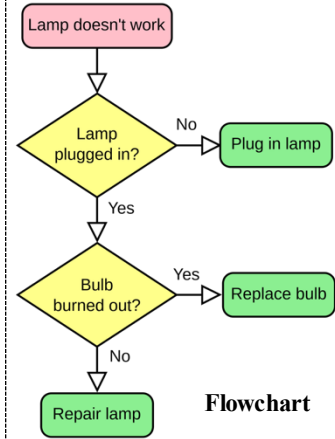
Infrastructure Graph



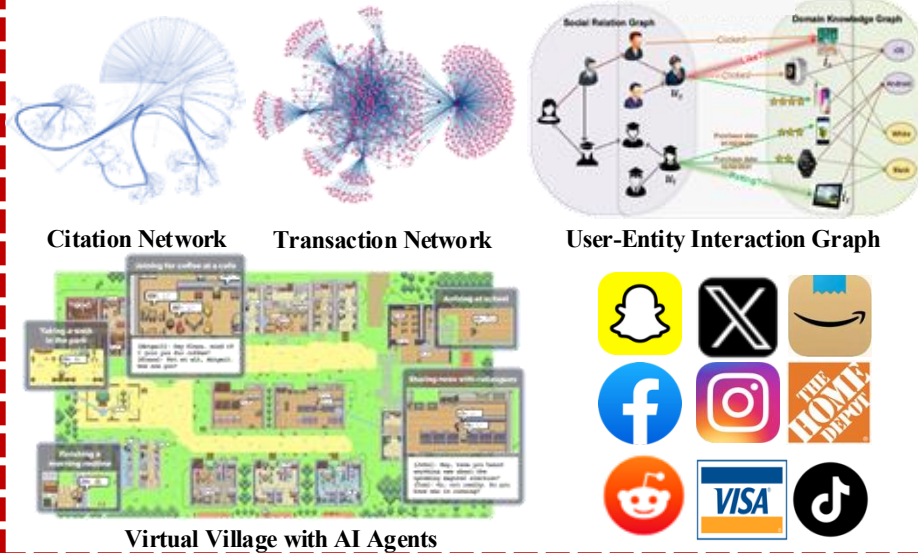
Transportation Network



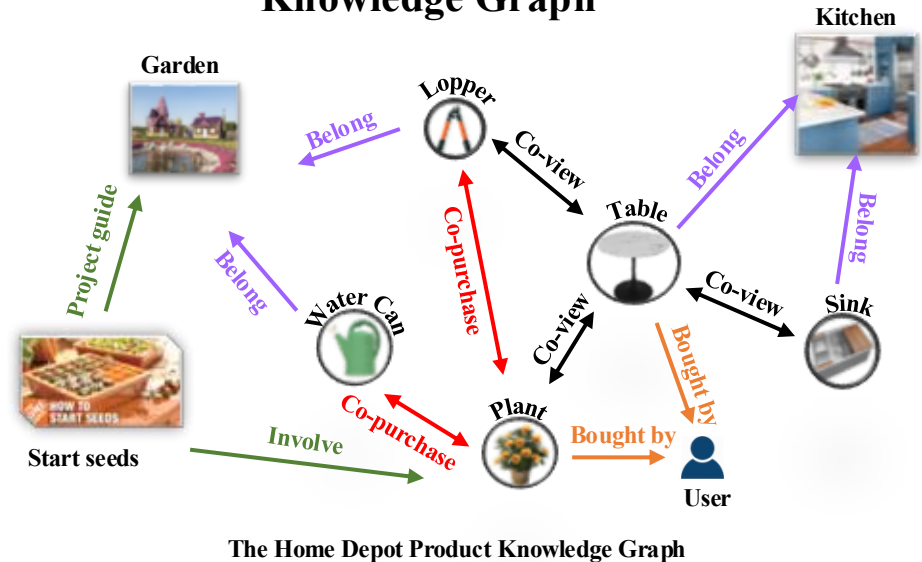
Decision Graph



Social Interaction Graph



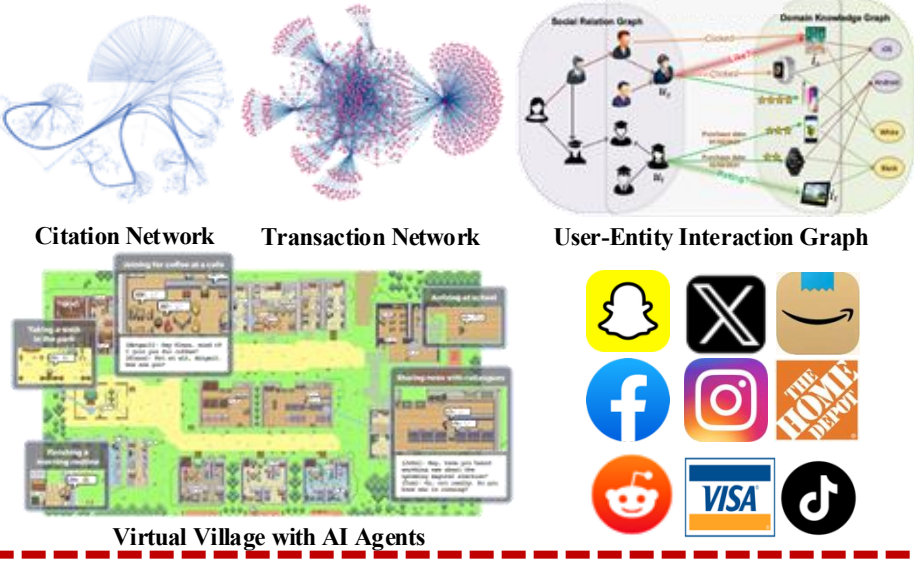
Knowledge Graph



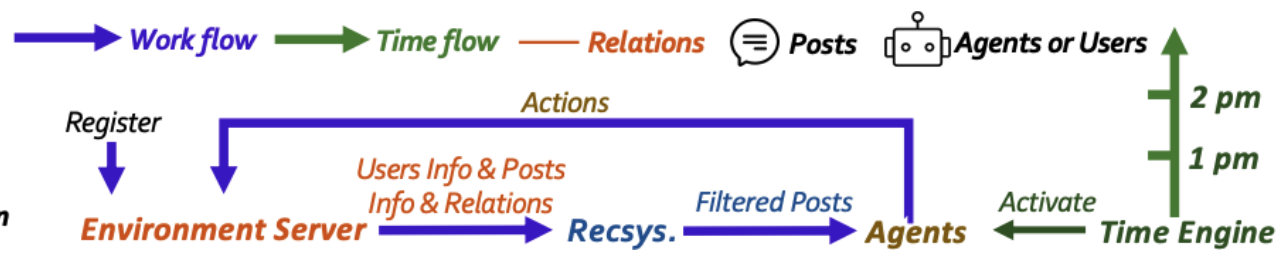
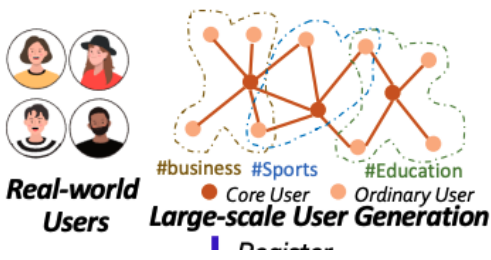
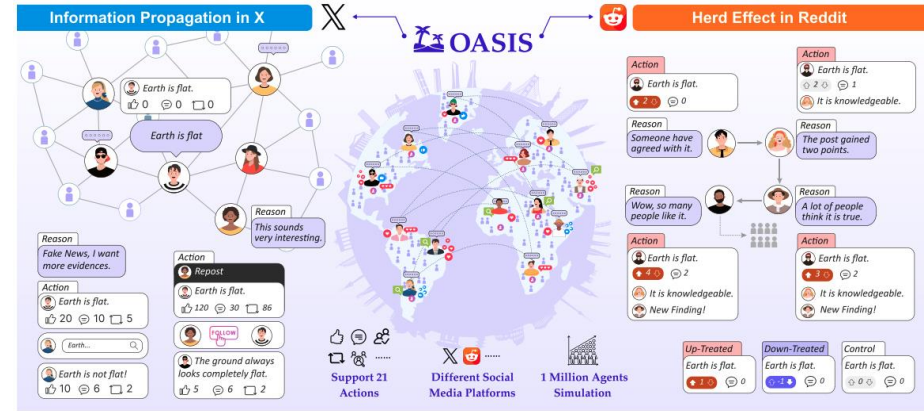


Macroscopic Graph Generation

Social Interaction Graph



Macroscopic Graph

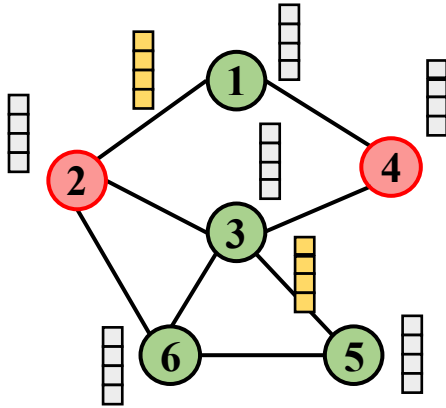




- **Graph Definition**
- **Graph Auto-Encoder**
- **Graph Generative Adversarial Network**
- **Graph Diffusion**
- **Feature and Topology**
- **Permutation Invariant**



Graph Definition

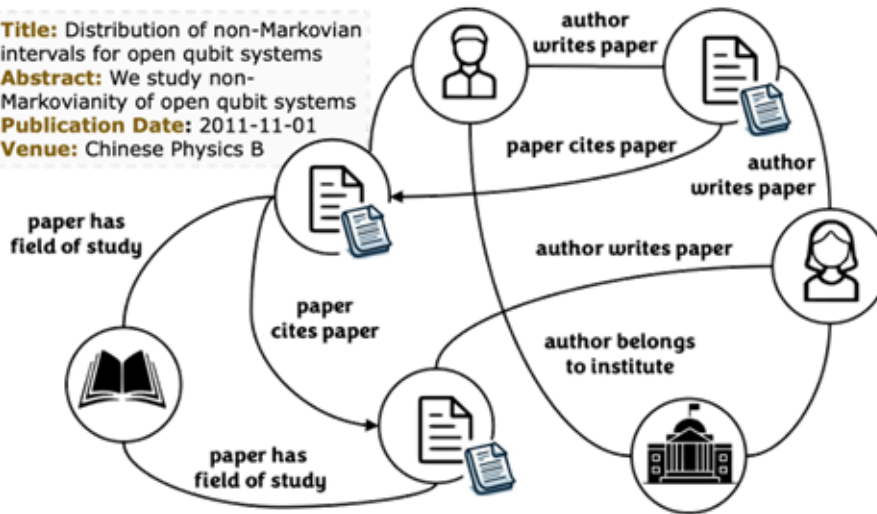


Node Attributes

Edge Attributes (Existence)

Graph Attributes

Title: Distribution of non-Markovian intervals for open qubit systems
Abstract: We study non-Markovianity of open qubit systems
Publication Date: 2011-11-01
Venue: Chinese Physics B

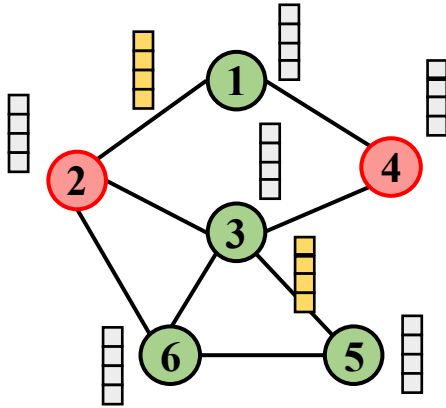


Academic Graph

MAG Semi-structured Knowledge Base



Graph Definition

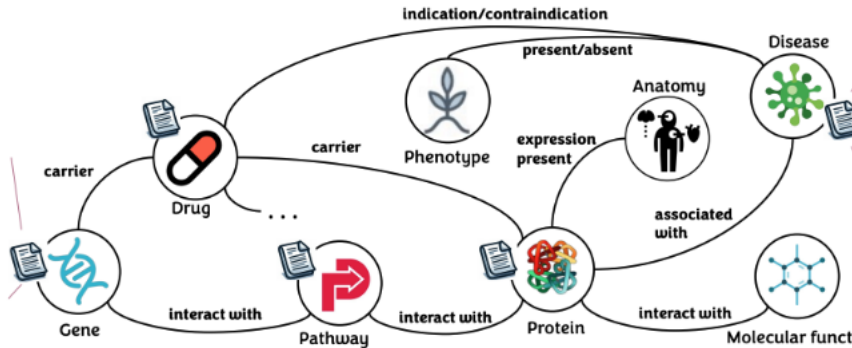


Node Attributes

Edge Attributes (Existence)

Graph Attributes

Name: GPANK1
Alias: DYRK1AP3, PAHX-AP, PAHXAP1
Description: This gene encodes a protein which is thought to play a role in immunity. Multiple alternatively spliced variants, encoding the same protein, have been identified.

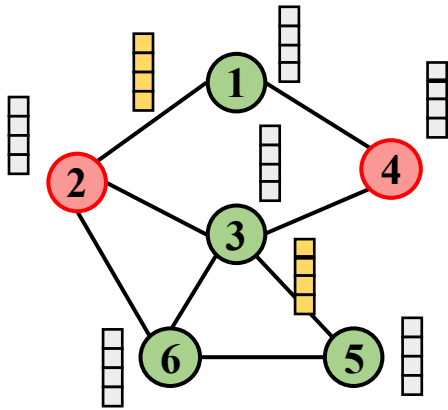


Prime Semi-structured Knowledge Base

Biomedical Graph



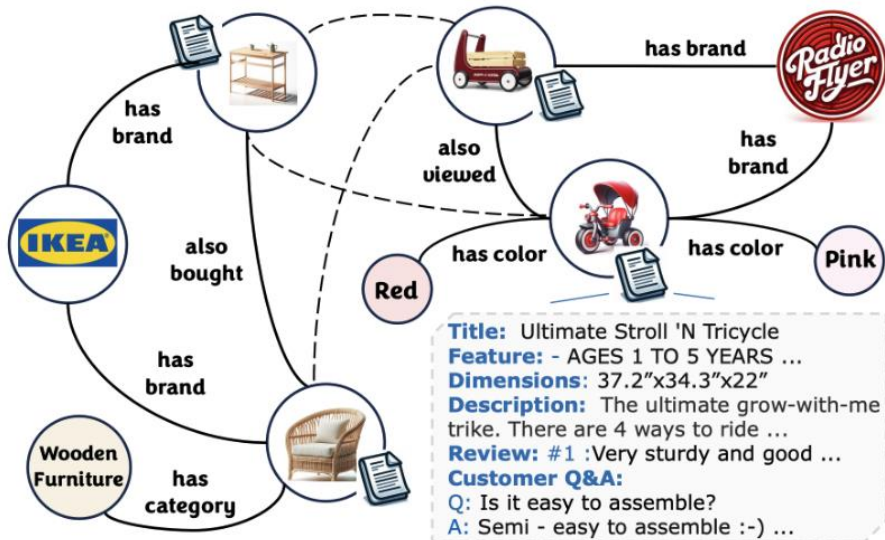
Graph Definition



Node Attributes

Edge Attributes (Existence)

Graph Attributes

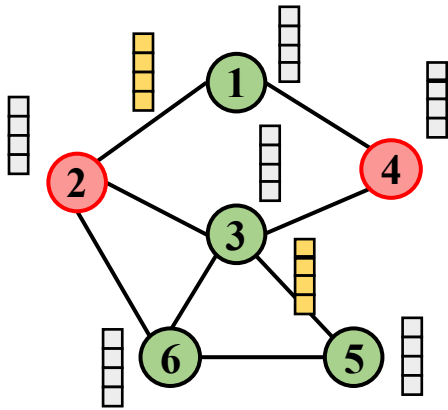


Amazon Semi-structured Knowledge Base

Amazon



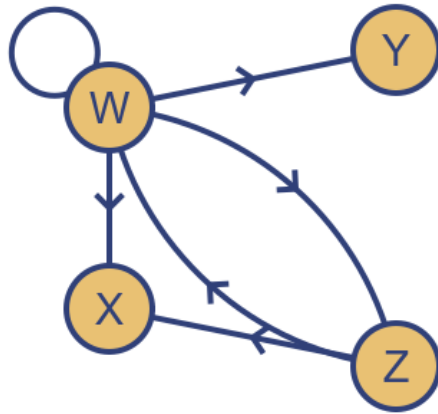
Graph Definition



Node Attributes $X \in \mathbb{R}^{6 \times K^{\text{node}}}$

Edge Attributes (Existence) $E \in \mathbb{R}^{8 \times K^{\text{Edge}}}$

Graph Attributes $Y \in \mathbb{R}^{1 \times K^{\text{Graph}}}$



Directed graph with loop

	W	X	Y	Z
W	1	1	1	1
X	0	0	0	0
Y	0	0	0	0
Z	1	1	0	0

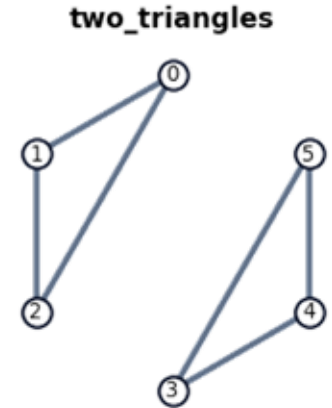
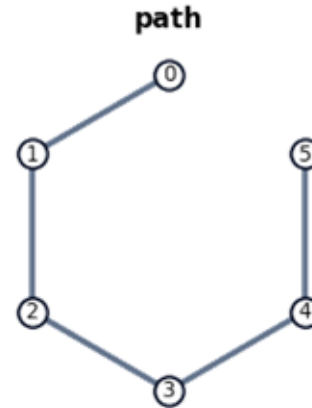
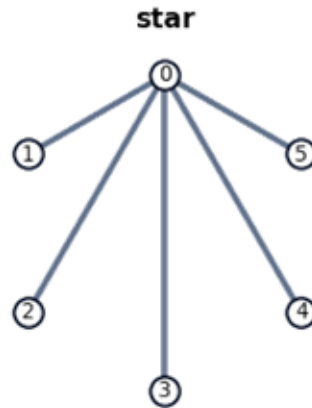
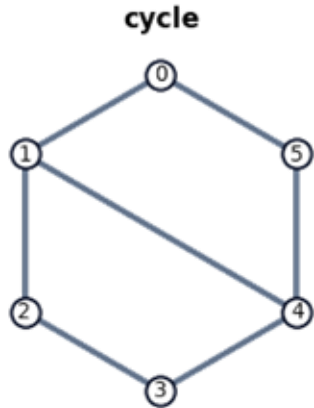


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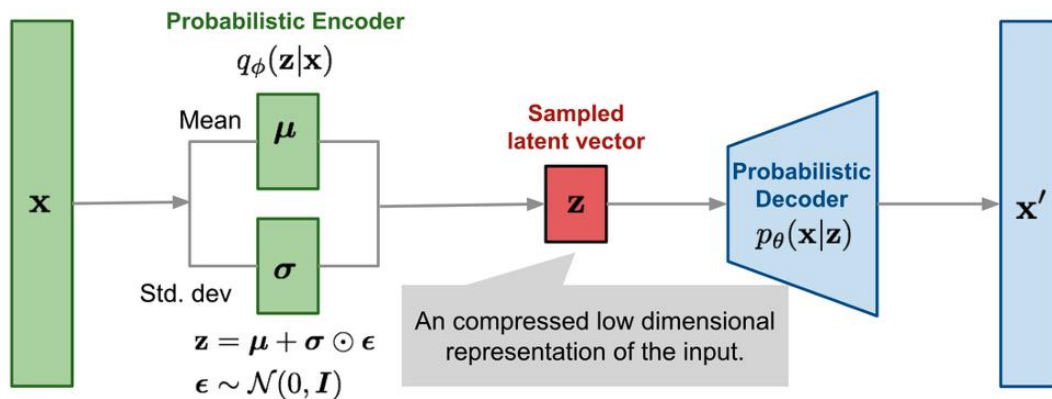
Microscopic Graph Generation - GraphVAE

Toy graph families



$$x \xrightarrow{\text{encoder}} q_{\phi}(z | x) \xrightarrow{\text{sample}} z \xrightarrow{\text{decoder}} p_{\theta}(x | z).$$

$$G \xrightarrow{\text{Encoder}} q_{\phi}(z | G) \xrightarrow{\text{Sample}} z \xrightarrow{\text{Decoder}} p_{\theta}(G | z)$$

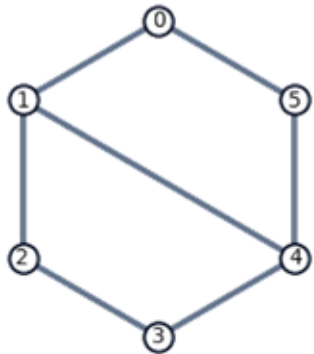




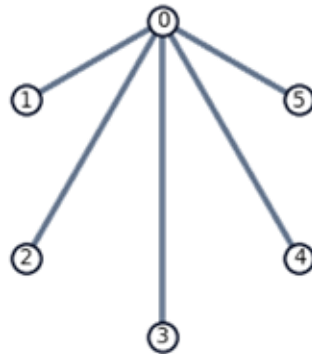
Microscopic Graph Generation - GraphVAE

Toy graph families

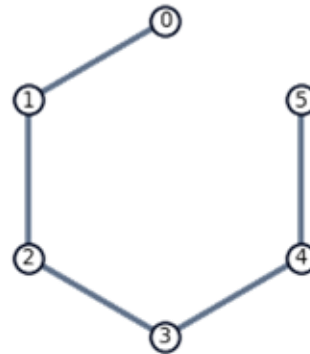
cycle



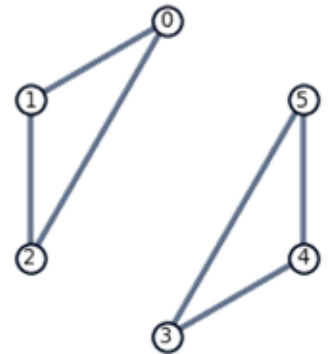
star



path



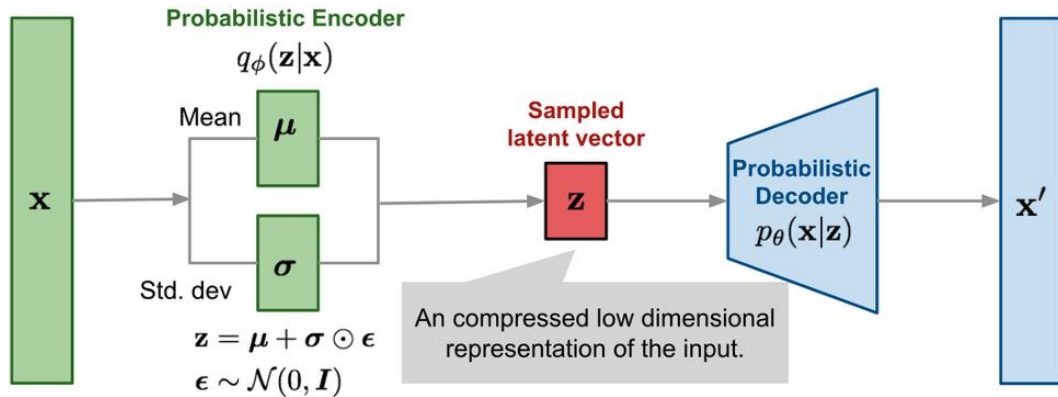
two_triangles



$$\mathcal{L}_{\text{VAE}} = \underbrace{\|x - \hat{x}\|^2}_{\text{Gaussian decoder} \Rightarrow \text{MSE}} + \underbrace{D_{\text{KL}}(q_{\phi}(z|x) || \mathcal{N}(0, I))}_{\text{KL regulariser}}$$

$$\mathcal{L}_{\text{G-VAE}} = -p_{\theta}(G^*|z) + D_{\text{KL}}(q_{\phi}(z|G^*) || \mathcal{N}(0, I))$$

$$\mathcal{L}_{\text{A-VAE}} = -p_{\theta}(A^*|z) + D_{\text{KL}}(q_{\phi}(z|A^*) || \mathcal{N}(0, I))$$

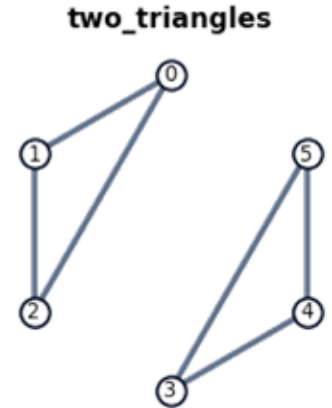
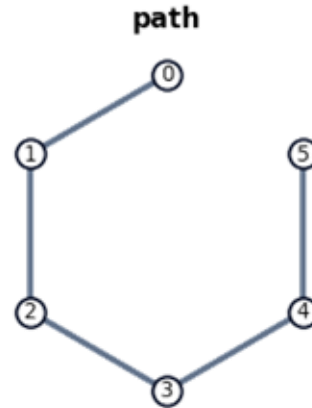
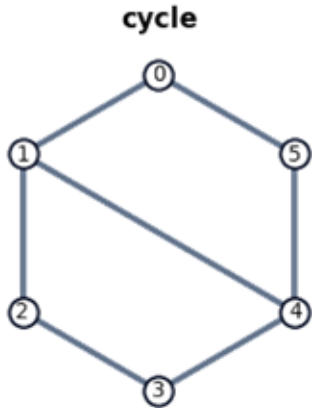


Maximum Likelihood



Microscopic Graph Generation - GraphVAE

Toy graph families

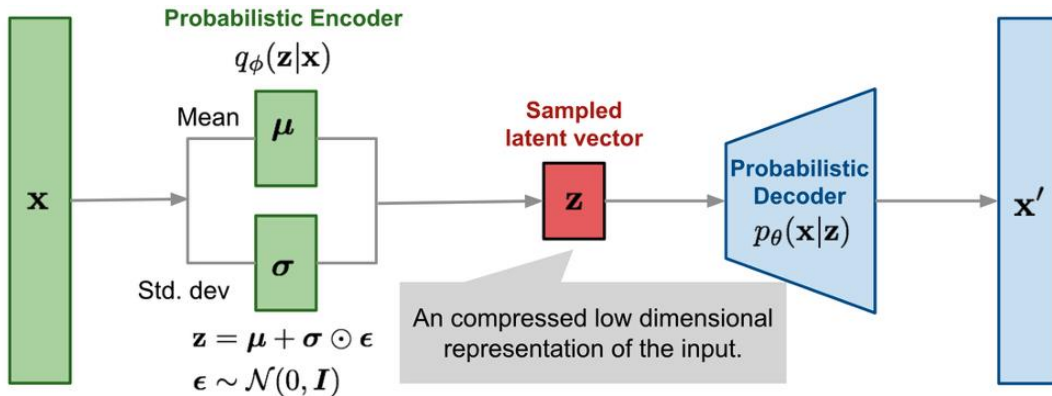


$$\mathcal{L}_{G-VAE} = -p_{\theta}(A^*|z) + D_{KL}(q_{\phi}(z|A^*) || \mathcal{N}(0, I))$$

$$p_{\theta}(A | z) = \prod_{i < j} \text{Bernoulli}(A_{ij}; \pi_{ij}(z)).$$

Maximum Likelihood

Bernoulli Distribution

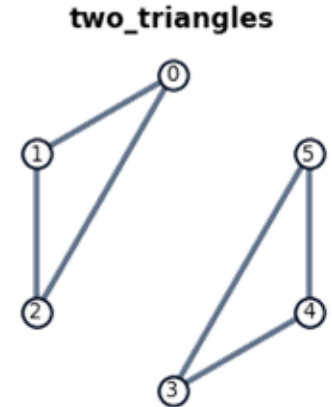
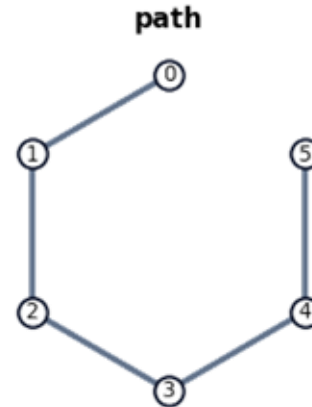
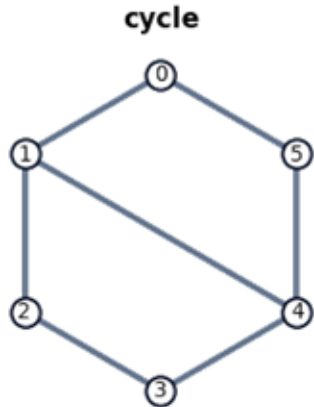


$$p_{\theta}(A|z) = \prod_{i < j} \pi_{ij}^{A_{ij}} (1 - \pi_{ij})^{1 - A_{ij}}$$



Microscopic Graph Generation - GraphVAE

Toy graph families



$$\mathcal{L}_{G\text{-VAE}} = \boxed{-p_{\theta}(A^*|z)} + D_{\text{KL}}(q_{\phi}(z|A^*) || \mathcal{N}(0, I))$$

Maximum Likelihood

$$p_{\theta}(A|z) = \prod_{i<j} \pi_{ij}^{A_{ij}} (1 - \pi_{ij})^{1-A_{ij}}$$

$$\mathcal{L}_{\text{edge}} = - \sum_{i<j} [A_{ij} \log \pi_{ij} + (1 - A_{ij}) \log(1 - \pi_{ij})].$$

Binary Cross Entropy Loss

$$\mathcal{L}_{\text{KL}} = -\frac{1}{2} \sum_{j=1}^d (1 + \log \sigma_j^2 - \mu_j^2 - \sigma_j^2)$$



Microscopic Graph Generation - GraphVAE

```
:class GraphVAE(nn.Module):
    def __init__(self, n_edges=N_EDGES, latent_dim=8, hidden=64, n_classes=4):
        super().__init__()
        self.encoder = nn.Sequential(
            nn.Linear(n_edges, hidden), nn.ReLU(),
            nn.Linear(hidden, hidden), nn.ReLU(),
        )
        self.mu = nn.Linear(hidden, latent_dim)
        self.logvar = nn.Linear(hidden, latent_dim)
        self.decoder = nn.Sequential(
            nn.Linear(latent_dim, hidden), nn.ReLU(),
            nn.Linear(hidden, hidden), nn.ReLU(),
            nn.Linear(hidden, n_edges),
        )
        self.class_centers = nn.Parameter(0.1 * torch.randn(n_classes, latent_dim))
```

```
def vae_loss(logits, x, mu, logvar, class_logits=None, labels=None, beta=0.05, gamma=1.0):
    recon = F.binary_cross_entropy_with_logits(logits, x, reduction="sum") / x.size(0)
    kl = -0.5 * torch.sum(1 + logvar - mu.pow(2) - logvar.exp()) / x.size(0)
    supervised = torch.zeros((), device=x.device)
    if class_logits is not None and labels is not None:
        supervised = F.cross_entropy(class_logits, labels)
    total = recon + beta * kl + gamma * supervised
    return total, recon.detach(), kl.detach(), supervised.detach()
```

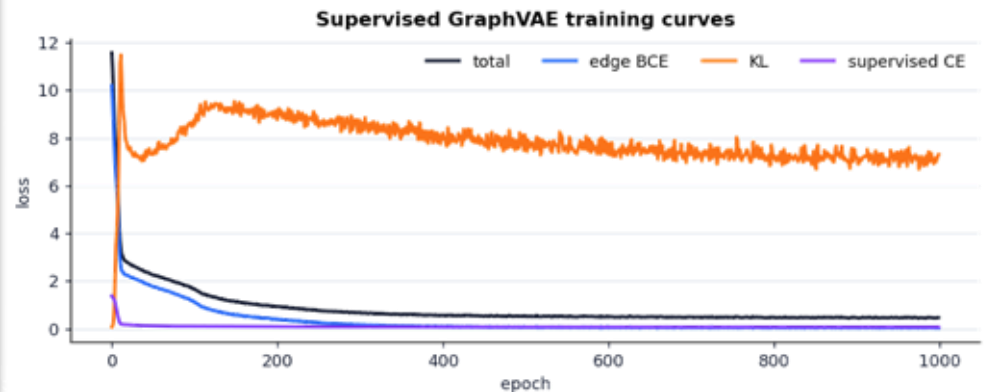
```
def encode(self, x):
    h = self.encoder(x)
    return self.mu(h), self.logvar(h)

def reparameterize(self, mu, logvar):
    std = torch.exp(0.5 * logvar)
    eps = torch.randn_like(std)
    return mu + eps * std

def decode_logits(self, z):
    return self.decoder(z)

def latent_class_logits(self, mu):
    # Higher score means closer to a learned class prototype in latent space.
    return -torch.cdist(mu, self.class_centers).pow(2)

def forward(self, x):
    mu, logvar = self.encode(x)
    z = self.reparameterize(mu, logvar)
    logits = self.decode_logits(z)
    return logits, mu, logvar
```

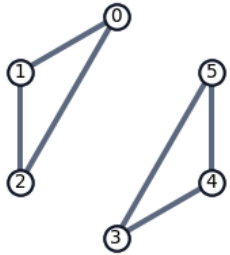




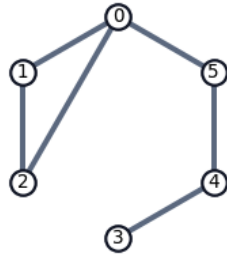
Microscopic Graph Generation - GraphVAE

GraphVAE hard samples

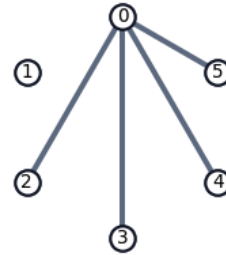
VAE sample 1
6 edges



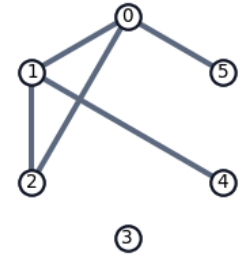
VAE sample 2
6 edges



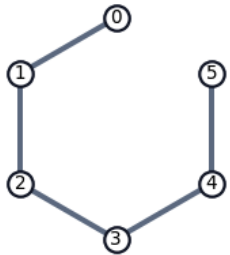
VAE sample 3
4 edges



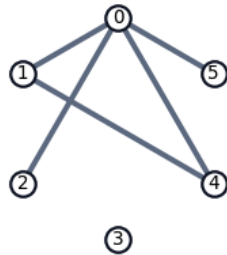
VAE sample 4
5 edges



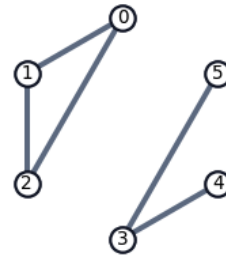
VAE sample 5
5 edges



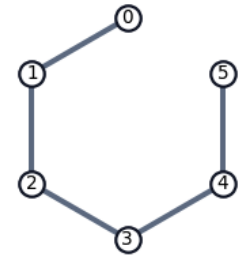
VAE sample 6
5 edges



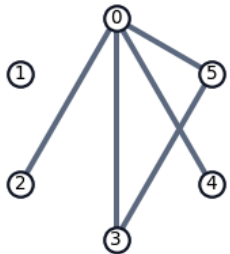
VAE sample 7
5 edges



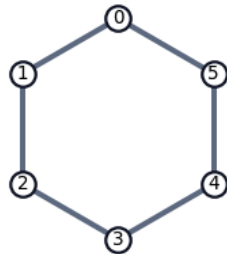
VAE sample 8
5 edges



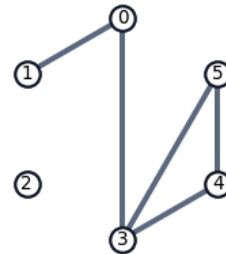
VAE sample 9
5 edges



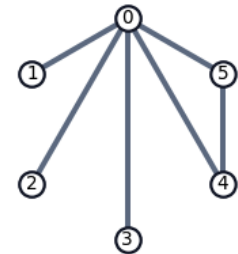
VAE sample 10
6 edges



VAE sample 11
5 edges

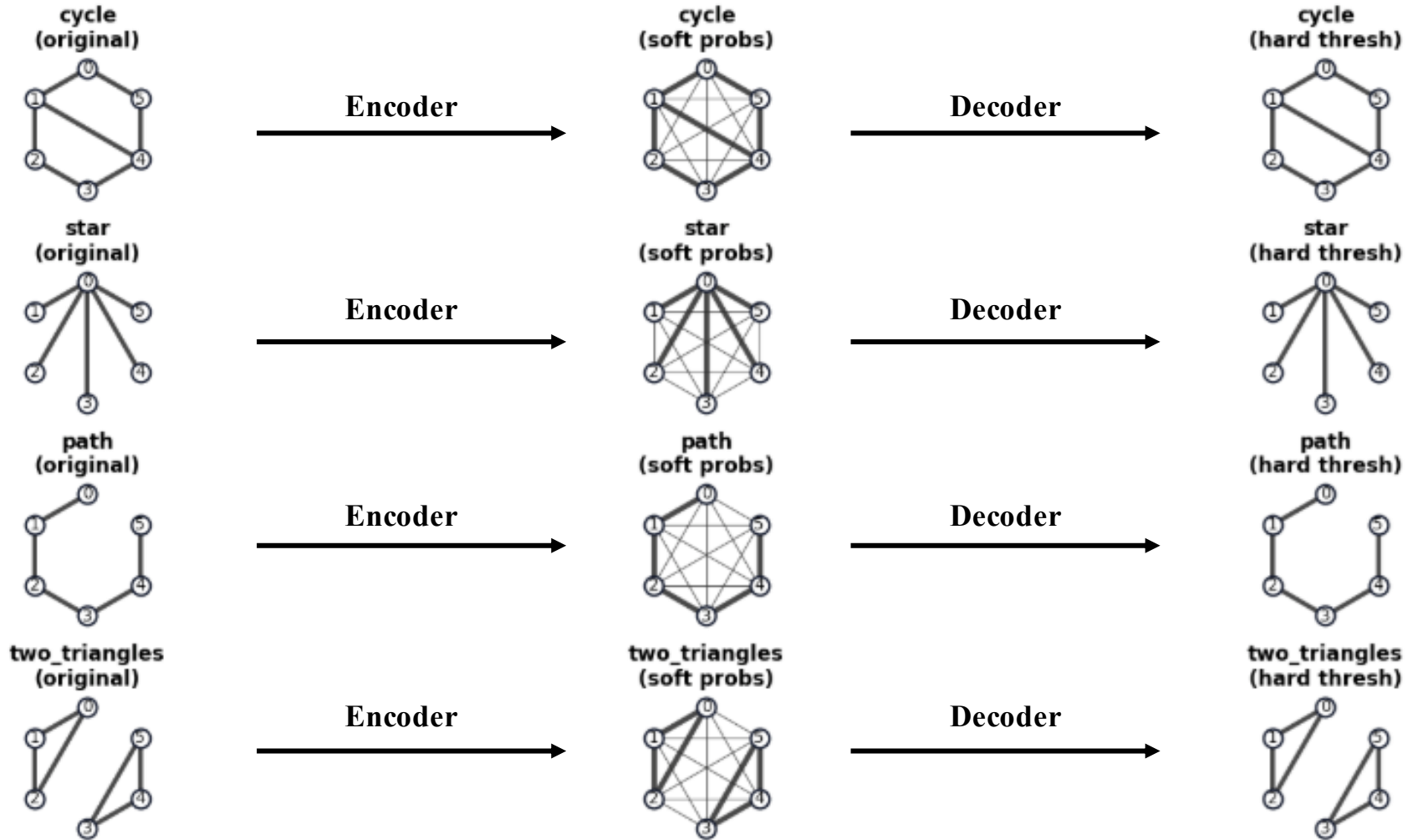


VAE sample 12
6 edges



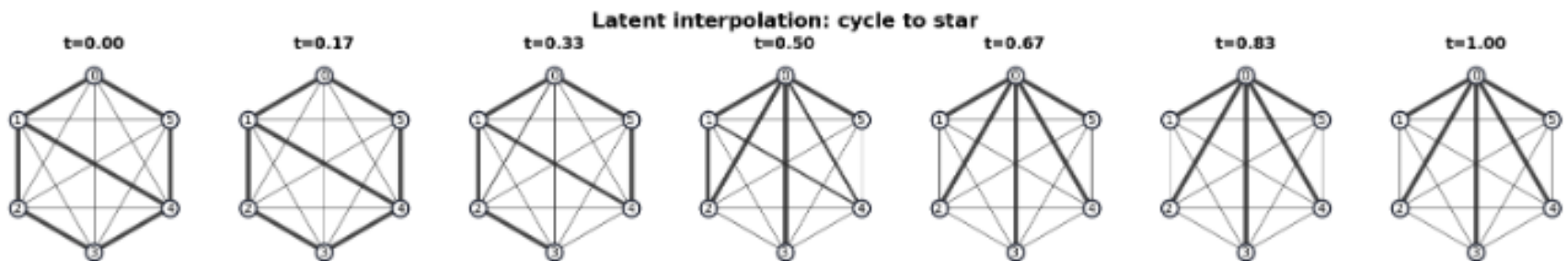
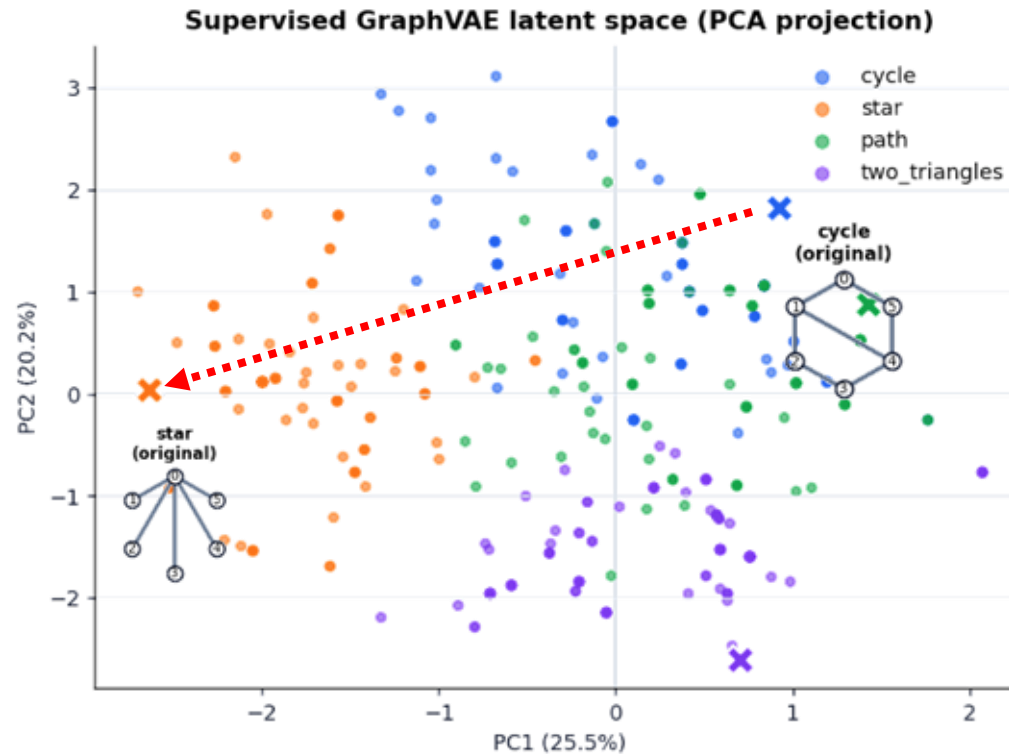


Microscopic Graph Generation - GraphVAE





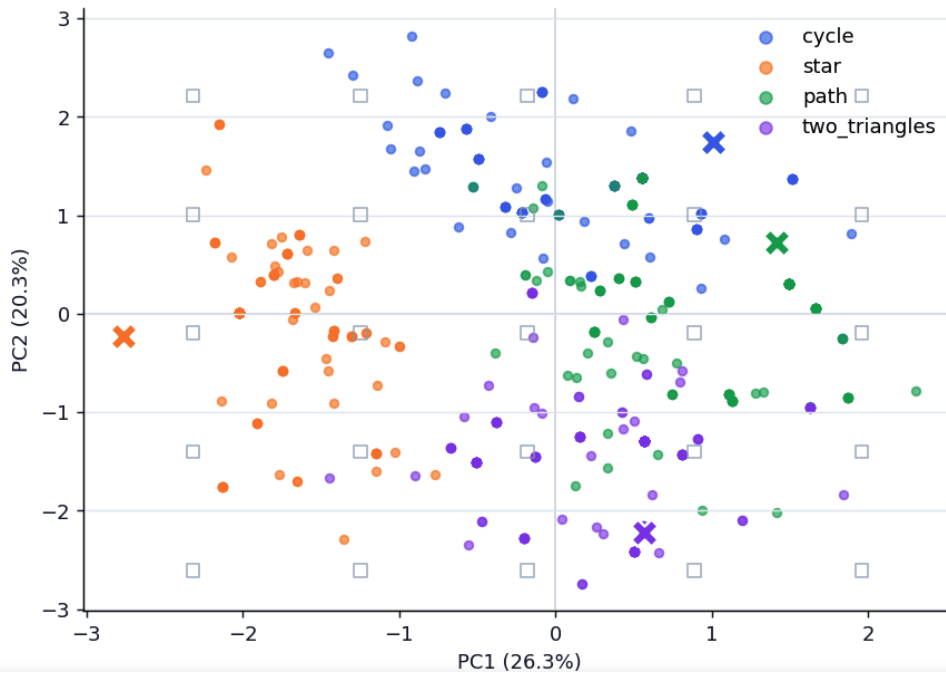
Microscopic Graph Generation - GraphVAE



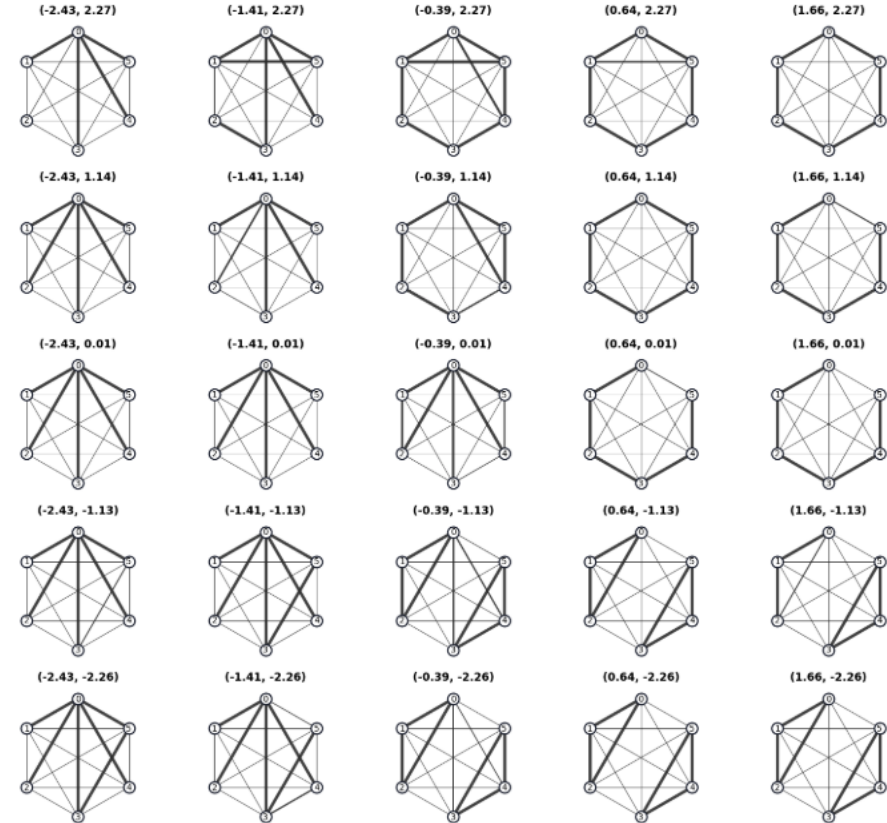


Microscopic Graph Generation - GraphVAE

Supervised GraphVAE latent space (PCA projection)



Generated graphs over a grid in (PC1, PC2) latent space

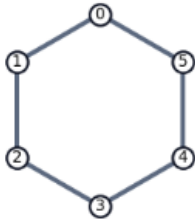




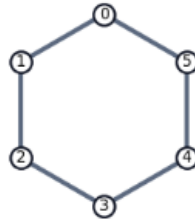
Microscopic Graph Generation – Conditional GraphVAE

$$q_{\phi}(z | A, y), \quad p_{\theta}(A | z, y).$$

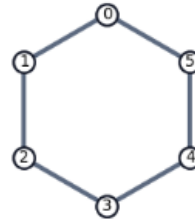
cVAE cycle
6 edges, d=0



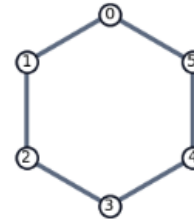
cVAE cycle
6 edges, d=0



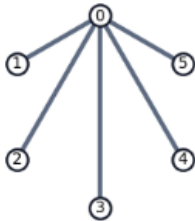
cVAE cycle
6 edges, d=0



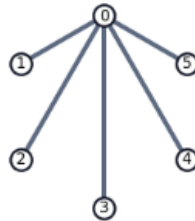
cVAE cycle
6 edges, d=0



cVAE star
5 edges, d=0



cVAE star
5 edges, d=0



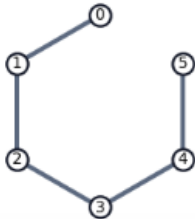
cVAE star
5 edges, d=0



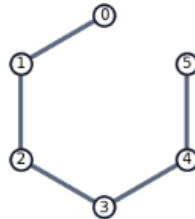
cVAE star
5 edges, d=0



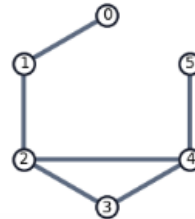
cVAE path
5 edges, d=0



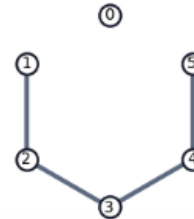
cVAE path
5 edges, d=0



cVAE path
6 edges, d=1



cVAE path
4 edges, d=1





Microscopic Graph Generation – Conditional GraphVAE

$$q_{\phi}(z \mid A, y), \quad p_{\theta}(A \mid z, y).$$

```
class ConditionalGraphVAE(nn.Module):
    def __init__(self, n_edges=N_EDGES, latent_dim=8, hidden=64, n_classes=4):
        super().__init__()
        self.n_classes = n_classes
        self.encoder = nn.Sequential(
            nn.Linear(n_edges + n_classes, hidden), nn.ReLU(),
            nn.Linear(hidden, hidden), nn.ReLU(),
        )
        self.mu = nn.Linear(hidden, latent_dim)
        self.logvar = nn.Linear(hidden, latent_dim)
        self.decoder = nn.Sequential(
            nn.Linear(latent_dim + n_classes, hidden), nn.ReLU(),
            nn.Linear(hidden, hidden), nn.ReLU(),
            nn.Linear(hidden, n_edges),
        )

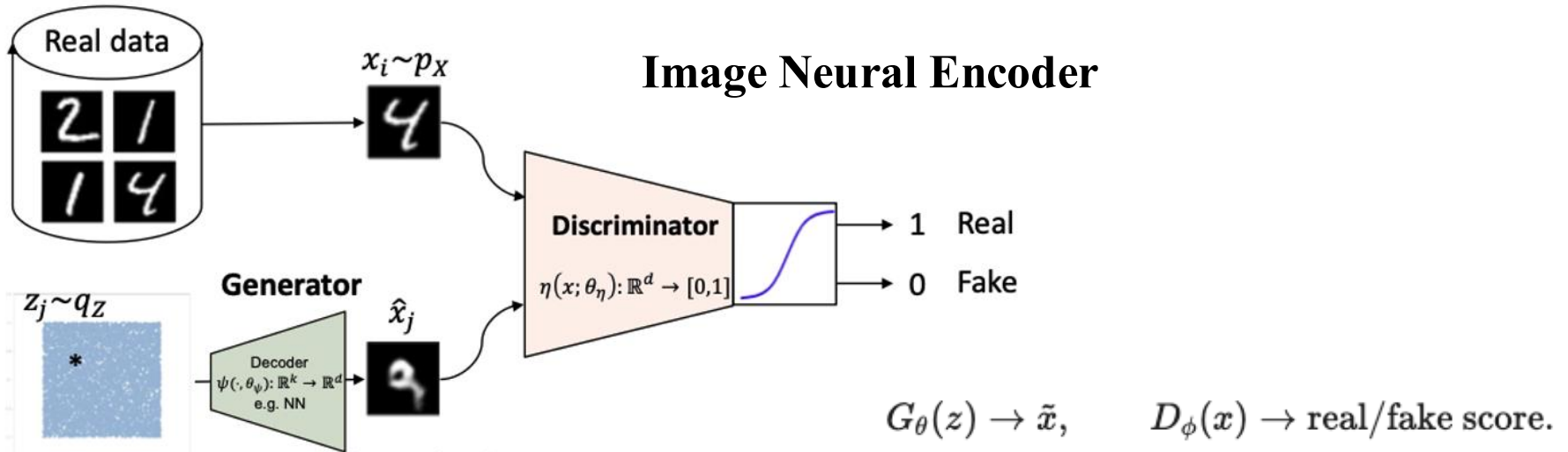
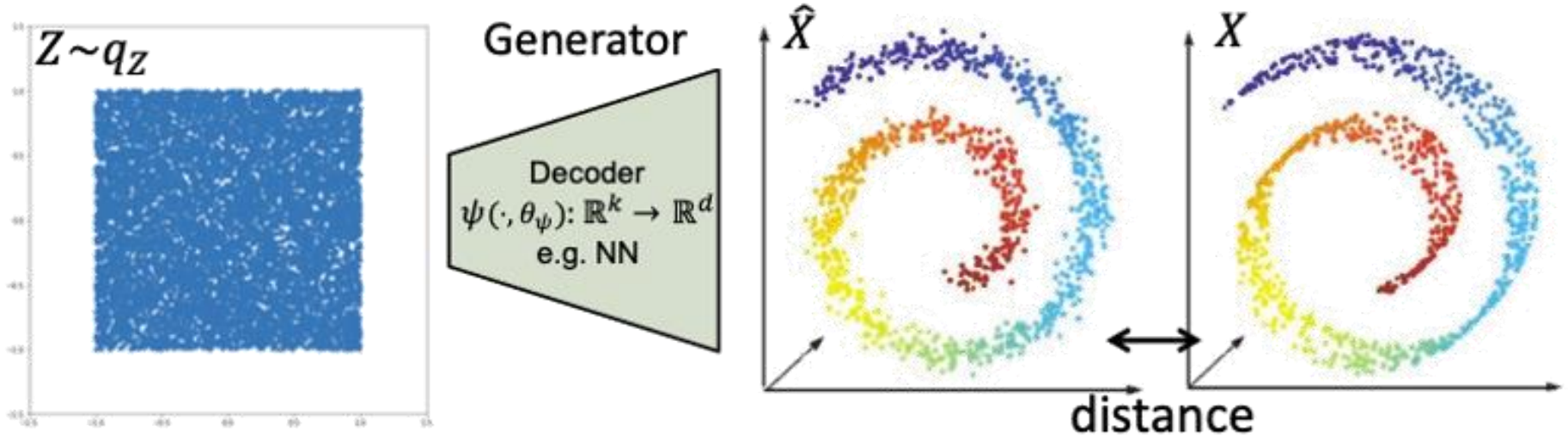
    def encode(self, x, labels):
        y = one_hot(labels, self.n_classes).to(x.device)
        h = self.encoder(torch.cat([x, y], dim=1))
        return self.mu(h), self.logvar(h)
```



- **Graph Definition**
- **Graph Auto-Encoder**
- **Graph Generative Adversarial Network**
- **Graph Diffusion**
- **Feature and Topology**
- **Permutation Invariant**

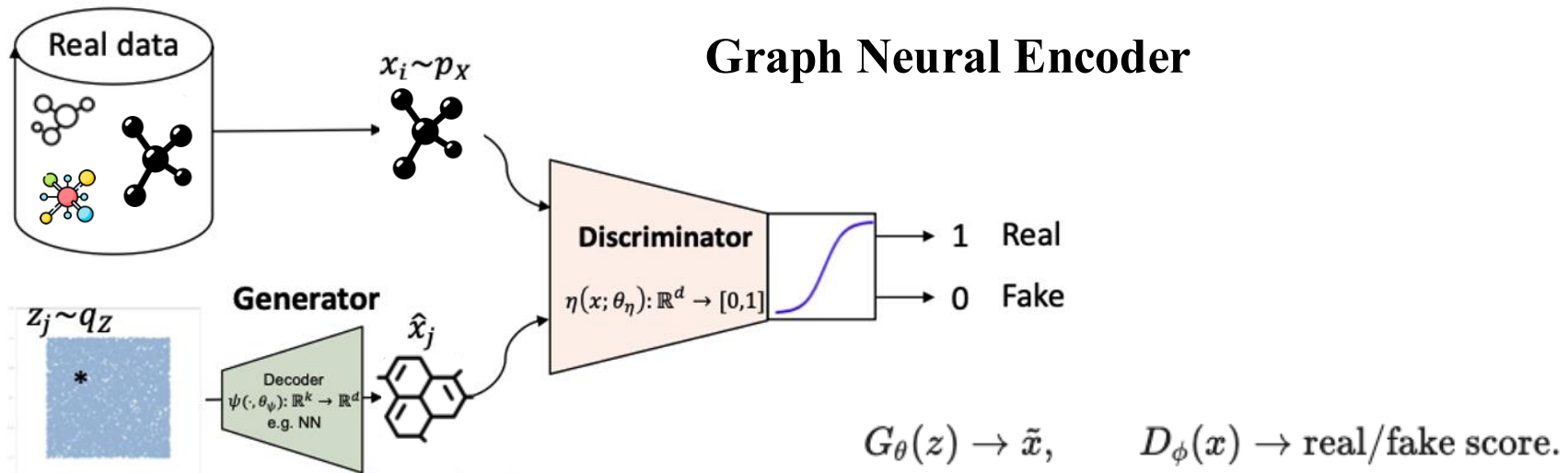


Graph GAN





Graph GAN

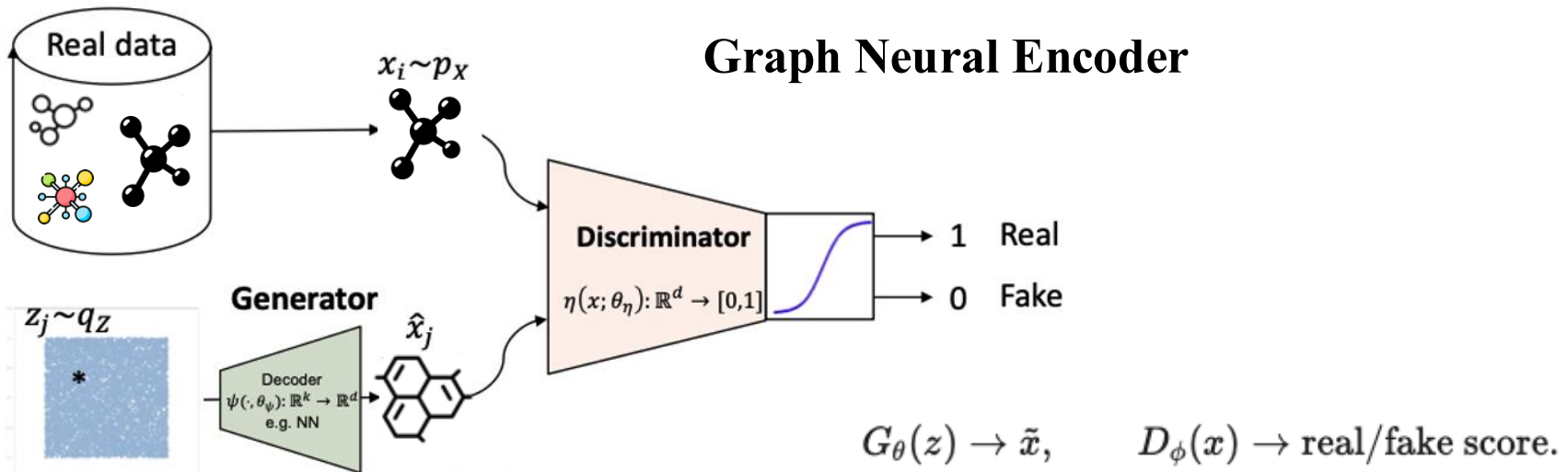


$$x \in \{0, 1\}^{N_{\text{edges}}}, \quad x_k = A_{ij} \text{ for one upper-triangular pair } (i, j).$$

$$\tilde{x}_k \sim \text{Bernoulli}(\pi_k(z)) \quad \text{or} \quad \tilde{x}_k = \mathbf{1}[\pi_k(z) \geq 0.5].$$



Graph GAN



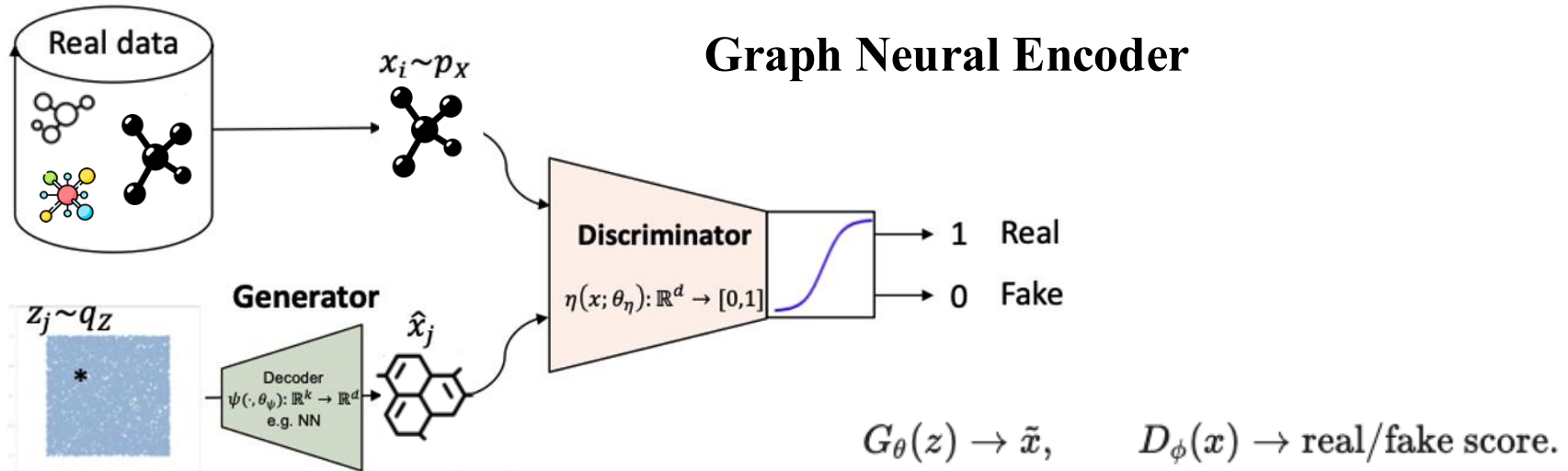
```
class GraphGenerator(nn.Module):
    def __init__(self, latent_dim=16, n_edges=N_EDGES, hidden=128):
        super().__init__()
        self.net = nn.Sequential(
            nn.Linear(latent_dim, hidden), nn.LeakyReLU(0.2),
            nn.Linear(hidden, hidden), nn.LeakyReLU(0.2),
            nn.Linear(hidden, hidden // 2), nn.LeakyReLU(0.2),
            nn.Linear(hidden // 2, n_edges),
        )

    def forward(self, z):
        return self.net(z)
```

```
class GraphDiscriminator(nn.Module):
    def __init__(self, n_edges=N_EDGES, hidden=64):
        super().__init__()
        self.net = nn.Sequential(
            nn.Linear(n_edges, hidden), nn.LeakyReLU(0.2),
            nn.Dropout(0.25),
            nn.Linear(hidden, hidden), nn.LeakyReLU(0.2),
            nn.Dropout(0.25),
            nn.Linear(hidden, 1),
        )
```



Graph GAN



$$\mathcal{L}_D = \frac{1}{2} \left[\text{BCE}(D(x_{\text{real}}), 1) + \text{BCE}(D(x_{\text{fake}}^{\text{detach}}), 0) \right]$$

$$\mathcal{L}_{G,\text{adv}} = \text{BCE}(D(x_{\text{fake}}), 1).$$

$$\mathcal{L}_{\text{FM}} = \|\mathbb{E}[x_{\text{fake}}] - \mathbb{E}[x_{\text{real}}]\|_2^2.$$

Edge Frequency Matching

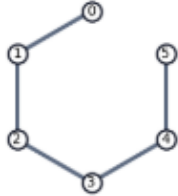
$$\mathcal{L}_G = \mathcal{L}_{G,\text{adv}} + \lambda_{\text{FM}} \mathcal{L}_{\text{FM}}.$$



Graph GAN

GraphGAN hard samples

GAN sample 1
5 edges, near path



GAN sample 2
6 edges, near two_triangles



GAN sample 3
5 edges, near star



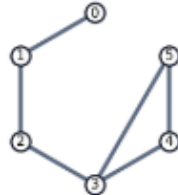
GAN sample 4
6 edges, near path



GAN sample 5
4 edges, near star



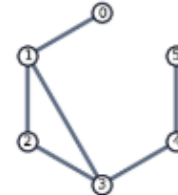
GAN sample 6
6 edges, near path



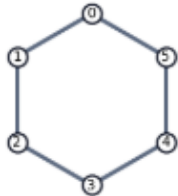
GAN sample 7
5 edges, near star



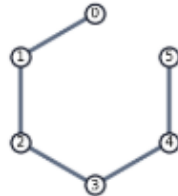
GAN sample 8
6 edges, near path



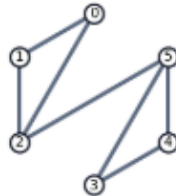
GAN sample 9
6 edges, near cycle



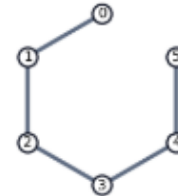
GAN sample 10
5 edges, near path



GAN sample 11
7 edges, near two_triangles



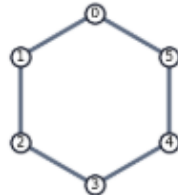
GAN sample 12
5 edges, near path



GAN sample 13
i edges, near two_triangles



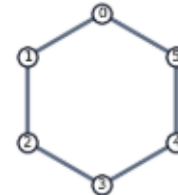
GAN sample 14
6 edges, near cycle



GAN sample 15
5 edges, near star



GAN sample 16
6 edges, near cycle





Conditional Graph GAN

$$\ell = G_{\theta}([z, \text{onehot}(y)]), \quad x_{\text{fake}} = \sigma(\ell).$$

```
class ConditionalGraphGenerator(nn.Module):
    def __init__(self, latent_dim=16, n_edges=N_EDGES, hidden=128, n_classes=4):
        super().__init__()
        self.n_classes = n_classes
        self.net = nn.Sequential(
            nn.Linear(latent_dim + n_classes, hidden), nn.LeakyReLU(0.2),
            nn.Linear(hidden, hidden), nn.LeakyReLU(0.2),
            nn.Linear(hidden, hidden // 2), nn.LeakyReLU(0.2),
            nn.Linear(hidden // 2, n_edges),
        )

    def forward(self, z, labels):
        y = one_hot(labels, self.n_classes).to(z.device)
        return self.net(torch.cat([z, y], dim=1))
```

$$s = D_{\phi}([x, \text{onehot}(y)]).$$

```
class ConditionalGraphDiscriminator(nn.Module):
    def __init__(self, n_edges=N_EDGES, hidden=64, n_classes=4):
        super().__init__()
        self.n_classes = n_classes
        self.net = nn.Sequential(
            nn.Linear(n_edges + n_classes, hidden), nn.LeakyReLU(0.2),
            nn.Dropout(0.25),
            nn.Linear(hidden, hidden), nn.LeakyReLU(0.2),
            nn.Dropout(0.25),
            nn.Linear(hidden, 1),
        )

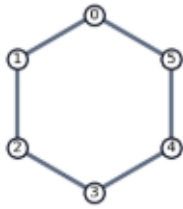
    def forward(self, x, labels):
        y = one_hot(labels, self.n_classes).to(x.device)
        return self.net(torch.cat([x, y], dim=1))
```



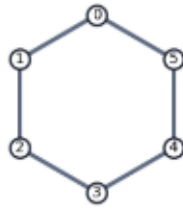
Conditional Graph GAN

Conditional GraphGAN thresholded samples

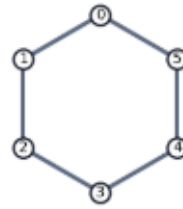
cGAN cycle
6 edges, $d=0$



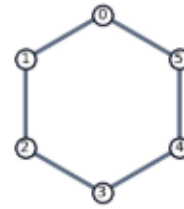
cGAN cycle
6 edges, $d=0$



cGAN cycle
6 edges, $d=0$



cGAN cycle
6 edges, $d=0$



cGAN star
5 edges, $d=0$



cGAN star
5 edges, $d=0$



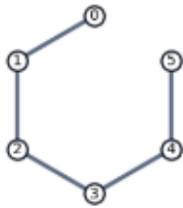
cGAN star
5 edges, $d=0$



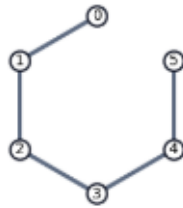
cGAN star
5 edges, $d=0$



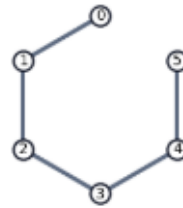
cGAN path
5 edges, $d=0$



cGAN path
5 edges, $d=0$



cGAN path
5 edges, $d=0$



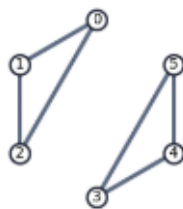
cGAN path
5 edges, $d=0$



cGAN two_triangles
6 edges, $d=0$



cGAN two_triangles
6 edges, $d=0$



cGAN two_triangles
6 edges, $d=0$



cGAN two_triangles
6 edges, $d=0$

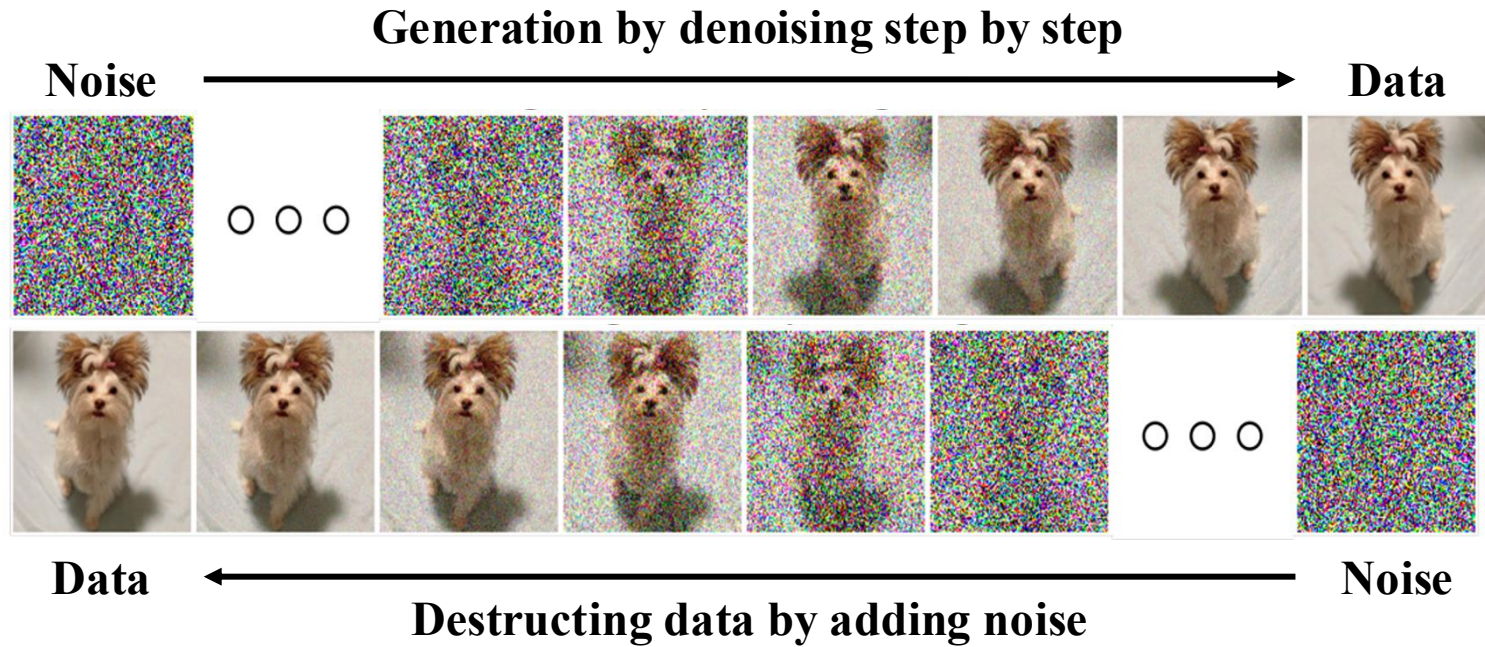




- **Graph Definition**
- **Graph Auto-Encoder**
- **Graph Generative Adversarial Network**
- **Graph Diffusion**
- **Feature and Topology**
- **Permutation Invariant**



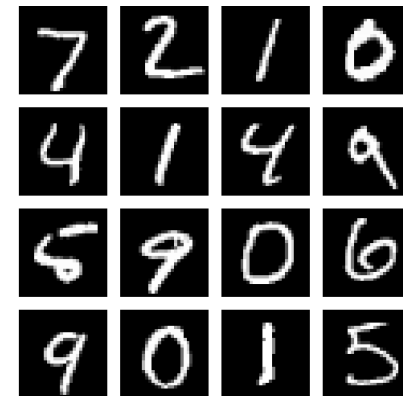
Graph Diffusion



$$q(x_t|x_{t-1}) \quad x_t \sim \mathcal{N}(\sqrt{\alpha_t}x_{t-1}, (1 - \alpha_t)I)$$

$$x_t \sim \mathcal{N}(\sqrt{\bar{\alpha}_t}x_0, (1 - \bar{\alpha}_t)I)$$

Forward diffusion: 1-0





Graph Diffusion

$$\theta^* = \operatorname{argmin} \mathbb{E}_{x_0 \sim p_{data}(x), t \sim U(1, T), \epsilon \sim \mathcal{N}(0, I)} \|\epsilon_\theta(x_t, t) - \epsilon\|_2^2$$

$$x_T \sim \mathcal{N}(0, I) \quad \hat{\epsilon} = \epsilon_{\theta^*}(x_t, t)$$

$$\tilde{\beta}_t = \frac{1 - \bar{\alpha}_{t-1}}{1 - \bar{\alpha}_t} \beta_t.$$

$$\hat{x}_0 = \frac{x_t - \sqrt{1 - \bar{\alpha}_t} \hat{\epsilon}}{\sqrt{\bar{\alpha}_t}}.$$

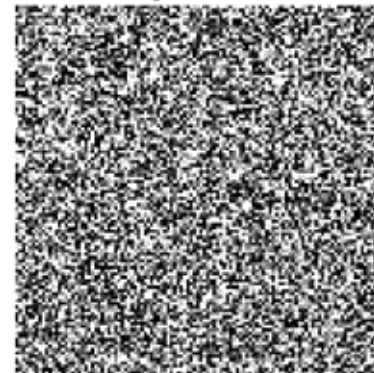
$$q(x_{t-1} | x_t, x_0) = \mathcal{N}(\tilde{\mu}_t(x_t, x_0), \tilde{\beta}_t I).$$

$$\tilde{\mu}_t(x_t, x_0) = \frac{\sqrt{\bar{\alpha}_{t-1}} \beta_t}{1 - \bar{\alpha}_t} x_0 + \frac{\sqrt{\bar{\alpha}_t} (1 - \bar{\alpha}_{t-1})}{1 - \bar{\alpha}_t} x_t$$

$$\mu_\theta(x_t, t) = \frac{1}{\sqrt{\alpha_t}} \left(x_t - \frac{\beta_t}{\sqrt{1 - \bar{\alpha}_t}} \epsilon_\theta(x_t, t) \right)$$

$$x_{t-1} = \mu_\theta(x_t, t) + \sqrt{\tilde{\beta}_t} z, \quad z \sim \mathcal{N}(0, I)$$

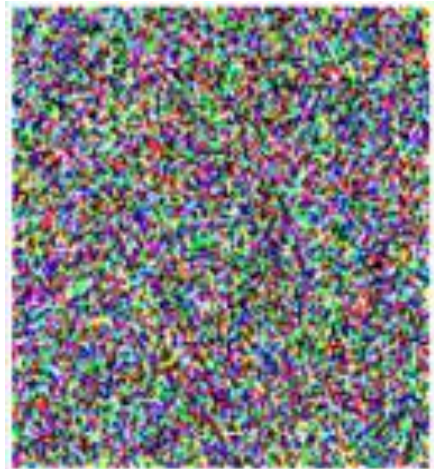
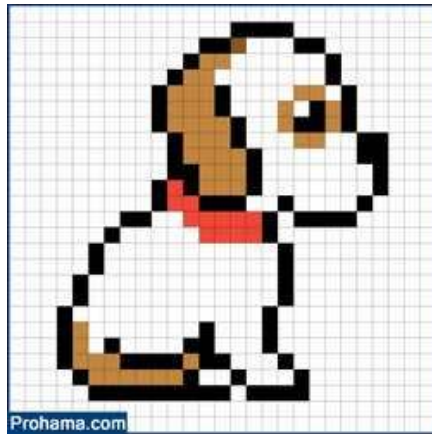
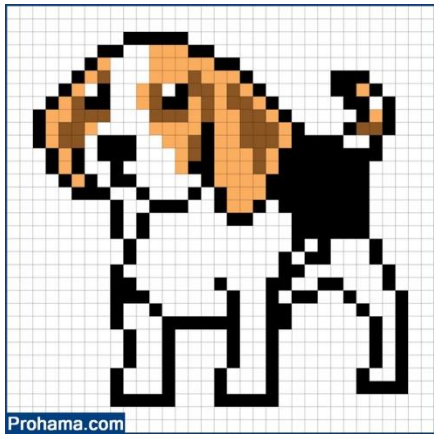
DDPM generation: t=200



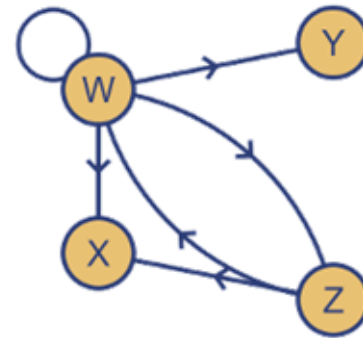


Graph Diffusion

Continuous Pixel

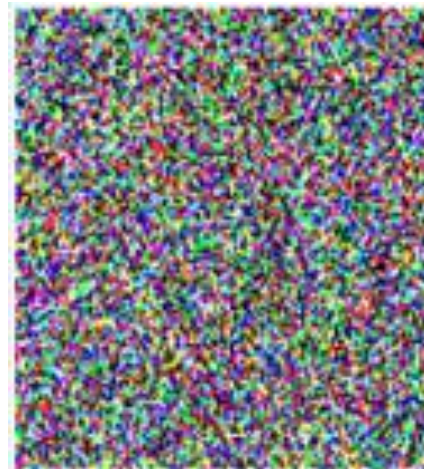


Discrete Label



Directed graph with loop

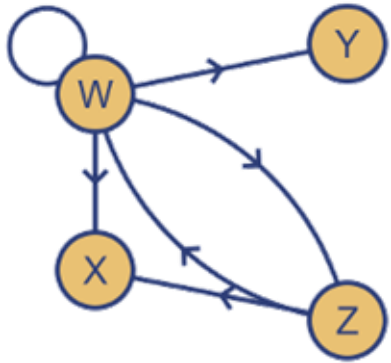
	W	X	Y	Z
W	1	1	1	1
X	0	0	0	0
Y	0	0	0	0
Z	1	1	0	0





Graph Diffusion

Discrete Label



Directed graph with loop

	W	X	Y	Z
W	1	1	1	1
X	0	0	0	0
Y	0	0	0	0
Z	1	1	0	0

Random
Flip

	W	X	Y	Z
W	0	1	0	0
X	1	1	0	1
Y	1	1	0	0
Z	1	0	1	0

$$q(x_t | x_{t-1}) : \quad x_t = x_{t-1} \oplus \eta_t, \quad \eta_t \sim \text{Bernoulli}(\beta_t).$$

$$Q_t = \begin{pmatrix} 1 - \beta_t & \beta_t \\ \beta_t & 1 - \beta_t \end{pmatrix}$$



Graph Diffusion

$$q(x_t | x_{t-1}) : x_t = x_{t-1} \oplus \eta_t, \quad \eta_t \sim \text{Bernoulli}(\beta_t).$$

State 1

State 2

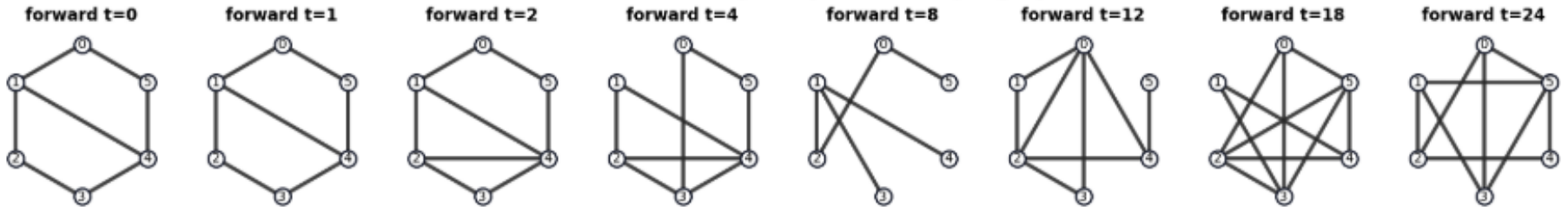
State Transition

$$Q_t = \begin{pmatrix} 1 - \beta_t & \beta_t \\ \beta_t & 1 - \beta_t \end{pmatrix}$$

State 1

State 2

Forward diffusion trajectory (one example graph)





Graph Diffusion

$$q(x_t | x_{t-1}) : x_t = x_{t-1} \oplus \eta_t, \quad \eta_t \sim \text{Bernoulli}(\beta_t).$$

	State 1	State 2	State Transition
$Q_t =$	$\begin{pmatrix} 1 - \beta_t & \beta_t \\ \beta_t & 1 - \beta_t \end{pmatrix}$		State 1
			State 2

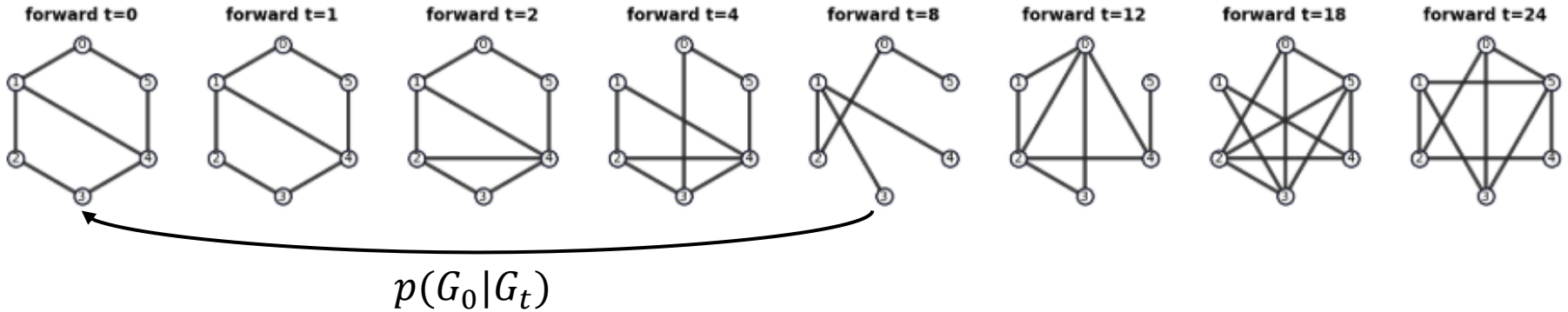
```
def corrupt_edges(x0, t):
    """Sample x_t ~ q(x_t | x0) for the flip Markov chain.

    x0: (B, E) binary. t: (B,) integer timesteps in [1, T_disc].
    Implemented by sampling an effective flip mask with probability flip_marginal[t].
    """
    p = flip_marginal[t].unsqueeze(1)
    flips = torch.bernoulli(torch.ones_like(x0) * p)
    return torch.abs(x0 - flips)
```



Graph Diffusion

Forward diffusion trajectory (one example graph)



$$p_\theta(x_0 | x_t, t).$$

$$\ell_\theta(x_t, t) \in \mathbb{R}^{N_{\text{edges}}}, \quad \hat{x}_0 = \sigma(\ell_\theta), \quad \mathcal{L} = \text{BCEWithLogits}(\ell_\theta, x_0).$$

1. Sample a clean graph vector x_0 from the dataset.
2. Sample a timestep $t \sim \text{Uniform}\{1, \dots, T\}$.
3. Corrupt: $x_t \leftarrow \text{corrupt_edges}(x_0, t)$.
4. Predict: $\ell \leftarrow \text{denoiser}(x_t, t)$.
5. Optimize: `BCEWithLogitsLoss(ℓ , x_0)`.

1. Initialize $x_T \sim \text{Bernoulli}(0.5)$ (random edges).
2. For $t = T, T - 1, \dots, 1$:
 - o Predict clean probabilities: $\hat{x}_0 \leftarrow \sigma(\text{model}(x_t, t))$.
 - o Make a hard estimate \tilde{x}_0 by thresholding (or Bernoulli sampling).
 - o To get the next state, we re-noise that estimate at the lower noise level

$$x_{t-1} \leftarrow \text{corrupt_edges}(\tilde{x}_0, t - 1).$$

3. Return the final hard sample x_0 .

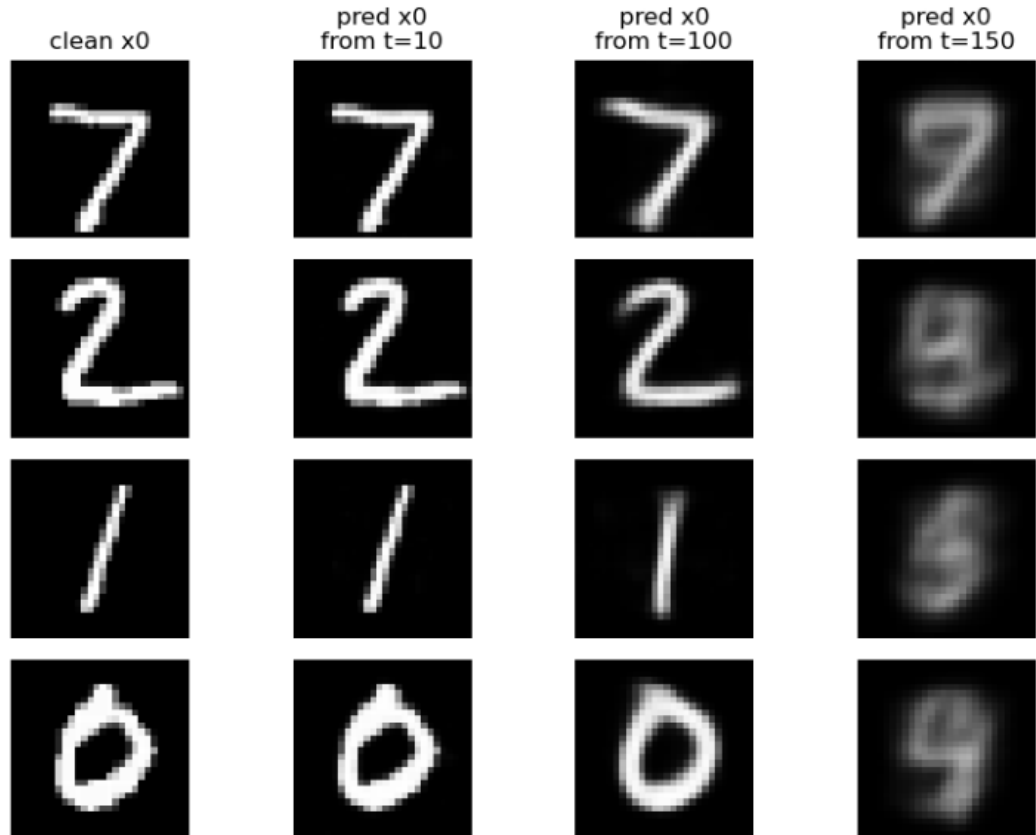
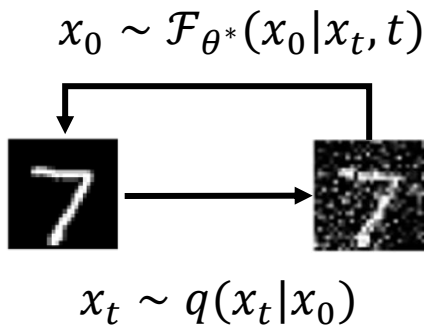


Graph Diffusion

$$\theta^* = \operatorname{argmin} \mathbb{E}_{x_0 \sim p_{\text{data}}(x), t \sim U(1, T), x_t \sim q(x_t | x_0)} \|\mathcal{F}_\theta(x_t, t) - x_0\|_2^2$$

$$x_T \sim \mathcal{N}(0, I)$$

$$\mathcal{F}_{\theta^*}(x_T, t) = \bar{x}_0$$



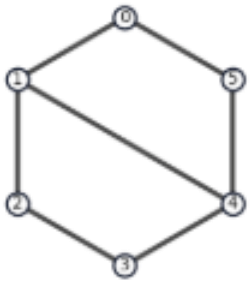
Predict from later time step gives more noisy images



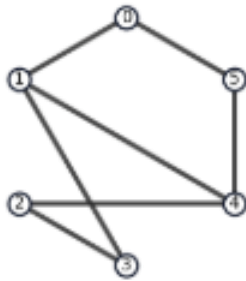
Graph Diffusion

Discrete diffusion: corruption and one-step denoising

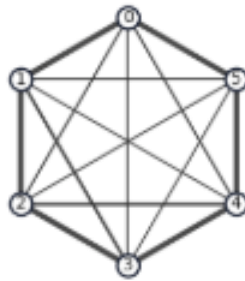
clean



corrupt t=4



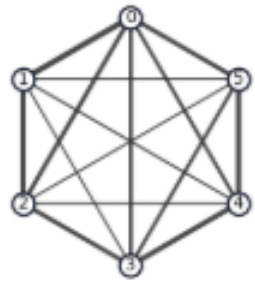
denoise t=4



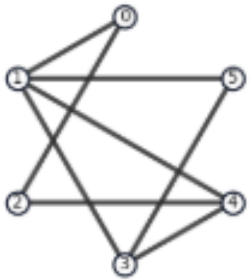
corrupt t=10



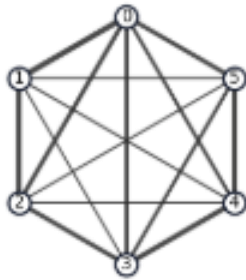
denoise t=10



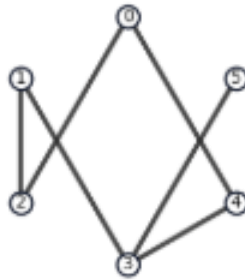
corrupt t=17



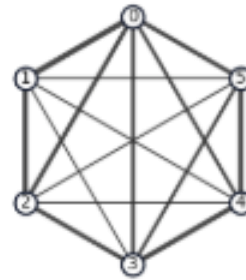
denoise t=17



corrupt t=24



denoise t=24

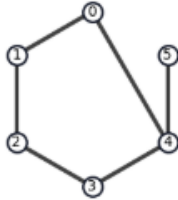




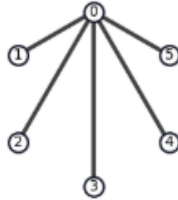
Graph Diffusion

Discrete diffusion generated graphs

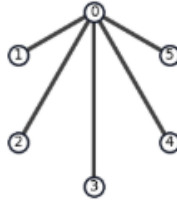
Diff sample 1
6 edges, near path



Diff sample 2
5 edges, near star



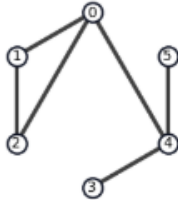
Diff sample 3
5 edges, near star



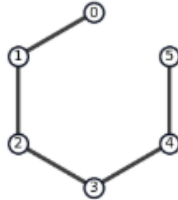
Diff sample 4
5 edges, near star



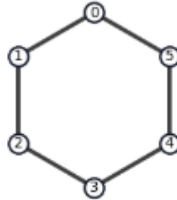
Diff sample 5
6 edges, near two_triangles



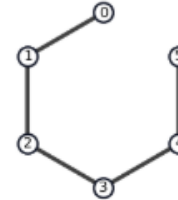
Diff sample 6
5 edges, near path



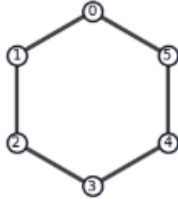
Diff sample 7
6 edges, near cycle



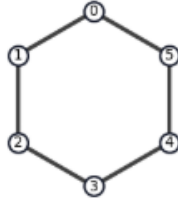
Diff sample 8
5 edges, near path



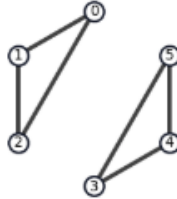
Diff sample 9
6 edges, near cycle



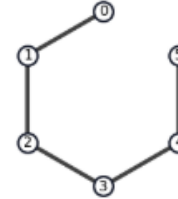
Diff sample 10
6 edges, near cycle



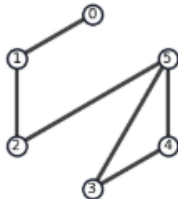
Diff sample 11
6 edges, near two_triangles



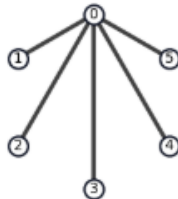
Diff sample 12
5 edges, near path



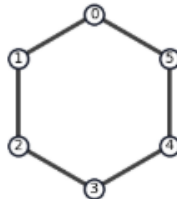
Diff sample 13
6 edges, near two_triangles



Diff sample 14
5 edges, near star



Diff sample 15
6 edges, near cycle



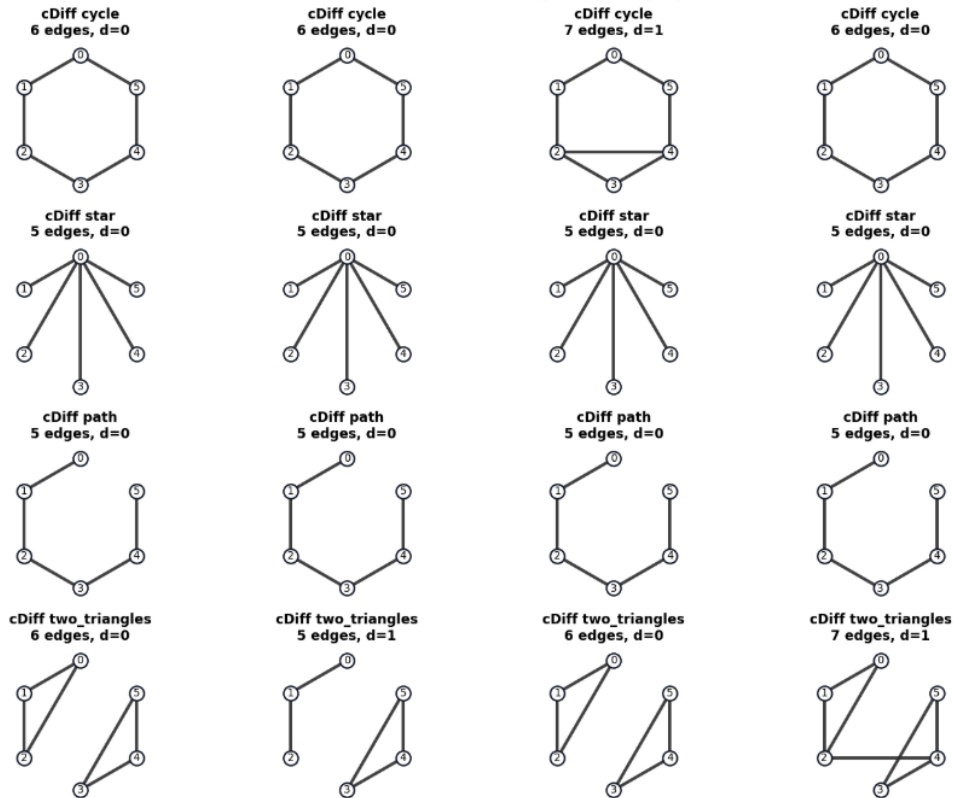
Diff sample 16
6 edges, near star



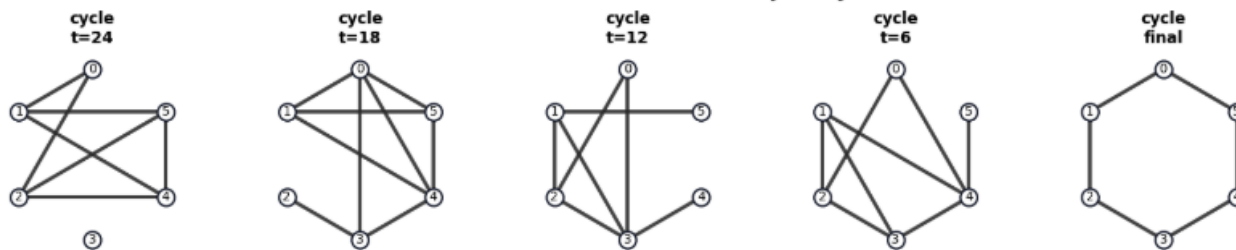


Graph Diffusion – Conditional Denoiser

Conditional discrete diffusion generated graphs



Conditional reverse diffusion trajectory



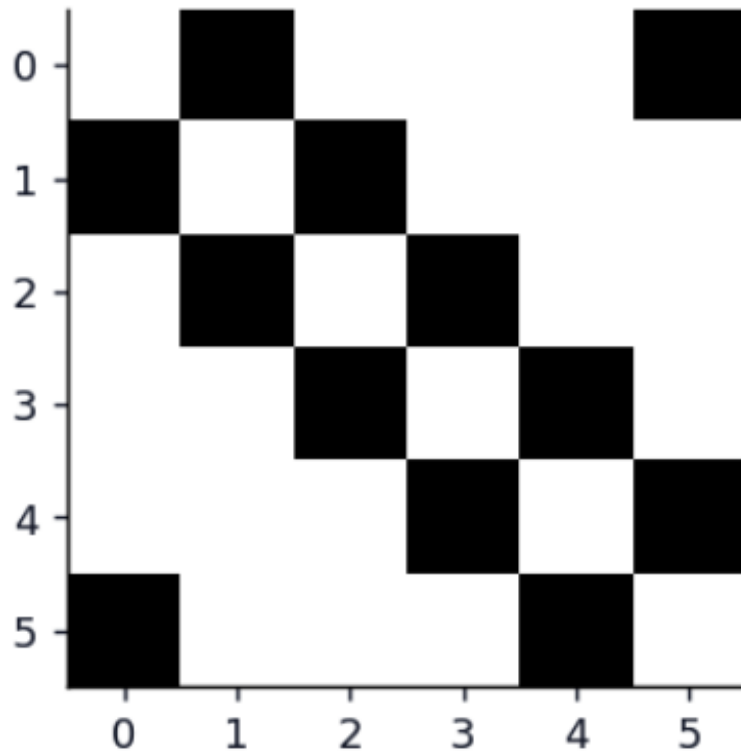


- **Graph Definition**
- **Graph Auto-Encoder**
- **Graph Generative Adversarial Network**
- **Graph Diffusion**
- **Challenges**
 - **Size of the graph**
 - **Feature and Topology**
 - **Permutation Invariant**

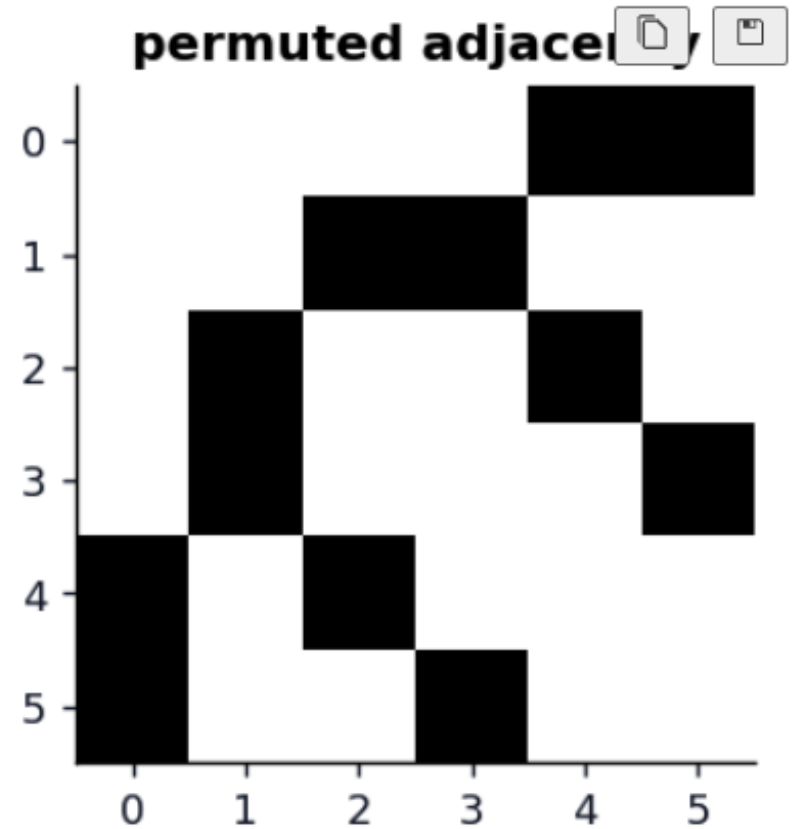


Overview

original adjacency



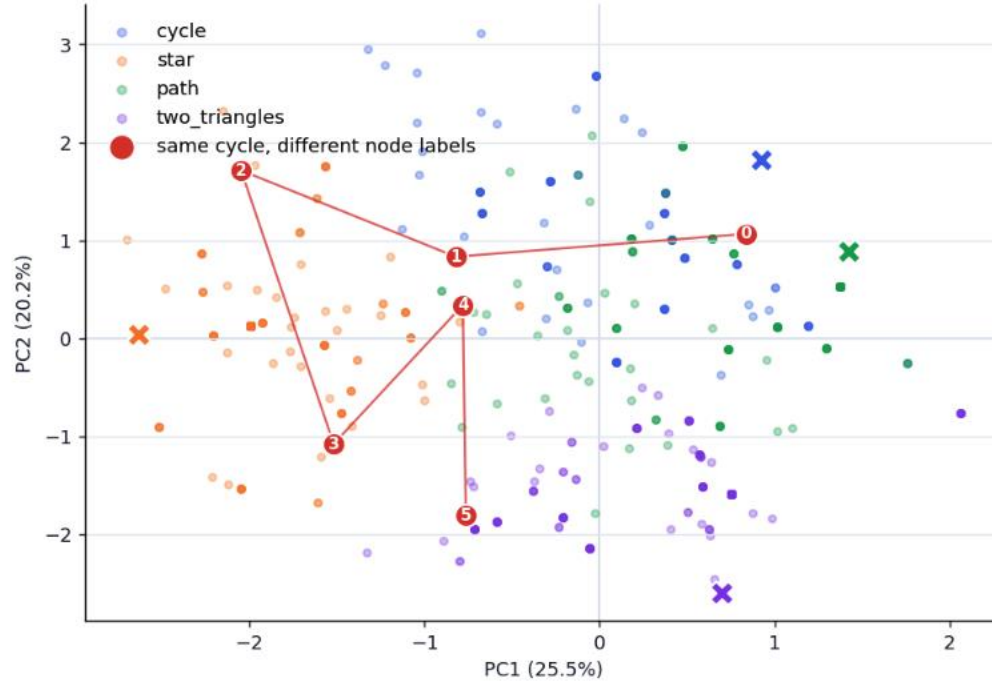
permuted adjacency



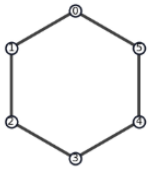


Overview

Supervised fixed-order GraphVAE: relabeled cycles move to different latent regions



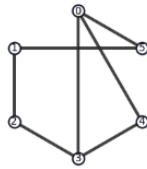
perm 0: pred cycle (0.98)
fixed err=0, match err=0



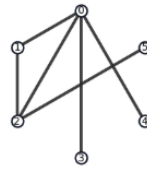
perm 1: pred cycle (0.66)
fixed err=3, match err=3



perm 2: pred star (0.81)
fixed err=3, match err=1



perm 3: pred star (0.98)
fixed err=8, match err=4



perm 4: pred path (0.62)
fixed err=4, match err=4



perm 5: pred two_triangles (0.97)
fixed err=2, match err=2

